FEATURES AND BENEFITS

- Functional safety
  - Developed in accordance with ISO 26262:2011 to meet ASIL B requirements (pending assessment)
  - Integrated background diagnostics for:
    - Signal path
    - Regulator
    - Hall plate and bias
    - Overtemperature detection
    - Nonvolatile memory
  - Defined fault state
- Multiple product options
  - Magnetic polarity, switchpoints, and hysteresis
  - Temperature coefficient
  - Output polarity
- Reduces module bill-of-materials (BOM) and assembly cost
  - ASIL B sensor can replace redundant sensors
  - Integrated overvoltage clamp and reverse-battery diode

DESCRIPTION

The APS12450 three-wire planar Hall-effect sensor integrated circuits (ICs) were developed in accordance with ISO 26262:2011 as a hardware safety element out of context with ASIL B capability (pending assessment) for use in automotive safety-related systems when integrated and used in the manner prescribed in the applicable safety manual and datasheet. The enhanced three-wire interface provides interconnect open/short diagnostics and a fault state to communicate diagnostic information while maintaining compatibility with legacy three-wire systems. The continuous background diagnostics are transparent to the host system and results in a reduced fault tolerant time.

The APS12450 product options include magnetic switchpoints, temperature coefficient, and output polarity. The response can be matched to SmCo, NdFeB, or low-cost ferrite magnets. For situations where a functionally equivalent three-wire switch device is preferred, refer to the APS11450.

PACKAGES

- 3-pin SOT23-W (LH)
- 3-pin ultramini SIP (UA)

TYPICAL APPLICATIONS

- Automotive and industrial safety systems
- Seat/window motors
- Sun roof/convertible top/tailgate/liftgate actuation
- Brake and clutch by wire actuators
- Engine management actuators
- Electric power steering (EPS)
- Transmission shift actuator

Continued on the next page...
FEATURES AND BENEFITS (continued)

- Automotive-grade ruggedness and fault tolerance
  - Extended AEC-Q100 Grade 0 qualification
    - Operation to 175°C junction temperature
  - 3 to 30 V operating voltage range
  - ±8 kV HBM ESD
  - Overtemperature indication

DESCRIPTION (continued)

APS12450 sensors are engineered to operate in the harshest environments with minimal external components. They are qualified beyond the requirements of AEC-Q100 Grade 0 and will survive extended operation at 175°C junction temperature.

These monolithic ICs include on-chip reverse-battery protection, overvoltage protection (e.g., 40 V load dump), ESD protection, overtemperature detection, and an internal voltage regulator for operation directly from an automotive battery bus. These integrated features reduce the end-product bill-of-materials (BOM) and assembly cost.

Package options include industry-standard surface-mount SOT (LH) and through-hole SIP (UA) packages. Both packages are RoHS-compliant and lead (Pb) free with 100% matte-tin-plated leadframes.

### SELECTION GUIDE [1]

<table>
<thead>
<tr>
<th>Part Number</th>
<th>Package</th>
<th>Packing</th>
<th>Output Polarity (B &gt; B_{OP})</th>
<th>Temperature Coefficient</th>
<th>Magnetic Operate Point, B_{OP} (typ)</th>
</tr>
</thead>
<tbody>
<tr>
<td>APS12450LLHALX-0SLA</td>
<td>3-pin SOT23W</td>
<td>13-in. reel, 10,000 pieces/reel</td>
<td>Low</td>
<td>0%/°C</td>
<td>22 G</td>
</tr>
<tr>
<td>APS12450LLHALT-0SLA</td>
<td>3-pin SOT23W</td>
<td>7-in. reel, 3000 pieces/reel</td>
<td>Low</td>
<td>0%/°C</td>
<td>50 G</td>
</tr>
<tr>
<td>APS12450LUAA-0SLA</td>
<td>3-pin SIP through-hole</td>
<td>bulk, 500 pieces/bag</td>
<td>Low</td>
<td>0%/°C</td>
<td>150 G</td>
</tr>
<tr>
<td>APS12450LLHALX-1SLA</td>
<td>3-pin SOT23W</td>
<td>13-in. reel, 10,000 pieces/reel</td>
<td>Low</td>
<td>0%/°C</td>
<td>50 G</td>
</tr>
<tr>
<td>APS12450LLHALT-1SLA</td>
<td>3-pin SOT23W</td>
<td>7-in. reel, 3000 pieces/reel</td>
<td>Low</td>
<td>0%/°C</td>
<td>150 G</td>
</tr>
<tr>
<td>APS12450LUAA-1SLA</td>
<td>3-pin SIP through-hole</td>
<td>bulk, 500 pieces/bag</td>
<td>Low</td>
<td>0%/°C</td>
<td>150 G</td>
</tr>
<tr>
<td>APS12450LLHALX-3SLA</td>
<td>3-pin SOT23W</td>
<td>13-in. reel, 10,000 pieces/reel</td>
<td>Low</td>
<td>0%/°C</td>
<td>150 G</td>
</tr>
<tr>
<td>APS12450LLHALT-3SLA</td>
<td>3-pin SOT23W</td>
<td>7-in. reel, 3000 pieces/reel</td>
<td>Low</td>
<td>0%/°C</td>
<td>150 G</td>
</tr>
<tr>
<td>APS12450LUAA-3SLA</td>
<td>3-pin SIP through-hole</td>
<td>bulk, 500 pieces/bag</td>
<td>Low</td>
<td>0%/°C</td>
<td>150 G</td>
</tr>
</tbody>
</table>

### ABSOLUTE MAXIMUM RATINGS

<table>
<thead>
<tr>
<th>Characteristic</th>
<th>Symbol</th>
<th>Notes</th>
<th>Rating</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>Supply Voltage [2]</td>
<td>( V_{CC} )</td>
<td></td>
<td>35</td>
<td>V</td>
</tr>
<tr>
<td>Reverse Supply Voltage</td>
<td>( V_{RCC} )</td>
<td></td>
<td>–30</td>
<td>V</td>
</tr>
<tr>
<td>Forward Output Voltage</td>
<td>( V_{OUT} )</td>
<td></td>
<td>30</td>
<td>V</td>
</tr>
<tr>
<td>Reverse Output Voltage</td>
<td>( V_{ROUT} )</td>
<td></td>
<td>–0.3</td>
<td>V</td>
</tr>
<tr>
<td>Output Current Sink</td>
<td>( I_{OUT(SINK)} )</td>
<td>VCC to VOUT</td>
<td>12</td>
<td>mA</td>
</tr>
<tr>
<td>Maximum Junction Temperature</td>
<td>( T_{J(MAX)} )</td>
<td>For 500 hours</td>
<td>165</td>
<td>°C</td>
</tr>
<tr>
<td>Storage Temperature</td>
<td>( T_{stg} )</td>
<td></td>
<td>–65 to 170</td>
<td>°C</td>
</tr>
</tbody>
</table>

[2] This rating does not apply to extremely short voltage transients such as load dump and/or ESD. Those events have individual ratings specific to the respective transient voltage event. Contact your local field applications engineer for information on EMC test results.
**PINOUT DIAGRAMS AND TERMINAL LIST**

---

**Terminal List Table**

<table>
<thead>
<tr>
<th>Name</th>
<th>Pin Number</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>LH</td>
<td>UA</td>
</tr>
<tr>
<td>VCC</td>
<td>1</td>
<td>1</td>
</tr>
<tr>
<td>VOUT</td>
<td>2</td>
<td>3</td>
</tr>
<tr>
<td>GND</td>
<td>3</td>
<td>2</td>
</tr>
</tbody>
</table>
OPERATING CHARACTERISTICS: Valid over full operating voltage and ambient temperature ranges for $T_J < T_{J,(\text{max})}$, unless otherwise specified.

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SUPPLY AND STARTUP</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Supply Voltage [2]</td>
<td>$V_{CC}$</td>
<td>Operating, $T_J &lt; 165^\circ C$</td>
<td>3.0</td>
<td>–</td>
<td>30</td>
<td>V</td>
</tr>
<tr>
<td>Supply Current</td>
<td>$I_{CC}$</td>
<td></td>
<td>–</td>
<td>–</td>
<td>4.5</td>
<td>mA</td>
</tr>
<tr>
<td>Power-On Time [3]</td>
<td>$t_{\text{on}}$</td>
<td>$V_{CC} &gt; V_{CC}(\text{min}), B &lt; B_{\text{RP}}(\text{min}) - 10 , \text{G}, B &gt; B_{\text{OF}}(\text{max}) + 10 , \text{G}$</td>
<td>–</td>
<td>–</td>
<td>150</td>
<td>$\mu$s</td>
</tr>
<tr>
<td>Power-On State</td>
<td>POS</td>
<td></td>
<td>$t &lt; t_{\text{on(max)}}$</td>
<td>$V_{OUT(FAULT)}$</td>
<td>–</td>
<td></td>
</tr>
<tr>
<td>Output Rise Time</td>
<td>$t_{\text{RISE}}$</td>
<td>See Applications Circuit, Figure 9: $V_{PU} = V_{CC}, R_{PU} = 3 , \text{k}\Omega, C_{OUT} = 1 , \text{nF}, I_{OUT} &lt; 12 , \text{mA}$</td>
<td>2</td>
<td>4</td>
<td>15</td>
<td>$\mu$s</td>
</tr>
<tr>
<td>Output Fall Time</td>
<td>$t_{\text{FALL}}$</td>
<td></td>
<td>2</td>
<td>4</td>
<td>15</td>
<td>$\mu$s</td>
</tr>
<tr>
<td>Output On Voltage</td>
<td>$V_{OUT(LOW)}$</td>
<td>Output ratiometric to $V_{PU}$; $V_{PU} = V_{CC}, \tau &lt; 3 , \mu\text{s}$,[5], $I_{OUT} &lt; 12 , \text{mA}$</td>
<td>10</td>
<td>20</td>
<td>30</td>
<td>%</td>
</tr>
<tr>
<td>Output Off Voltage</td>
<td>$V_{OUT(HIGH)}$</td>
<td></td>
<td>70</td>
<td>80</td>
<td>90</td>
<td>%</td>
</tr>
<tr>
<td>Output Off Voltage Overshoot [4]</td>
<td>$V_{OUT(HIGH)OVER}$</td>
<td>Overshoot percentage relative to $V_{PU}$ (see Figure 8); $V_{PU} = V_{CC}, \tau &lt; 3 , \mu\text{s}$,[5], $I_{OUT} &lt; 12 , \text{mA}$</td>
<td>–</td>
<td>2</td>
<td>–</td>
<td>%</td>
</tr>
<tr>
<td></td>
<td>$t_{\text{VOUT(H)OVER}}$</td>
<td>Duration of output voltage overshoot ($V_{OUT(HIGH)OVER}$)</td>
<td>–</td>
<td>–</td>
<td>5</td>
<td>$\mu$s</td>
</tr>
<tr>
<td><strong>ON-BOARD PROTECTION</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Fault Reaction Time</td>
<td>$I_{\text{DIAG}}$</td>
<td></td>
<td>–</td>
<td>25</td>
<td>60</td>
<td>$\mu$s</td>
</tr>
<tr>
<td>Diagnostics Fault Retry Time [6]</td>
<td>$I_{\text{DIAGF}}$</td>
<td></td>
<td>–</td>
<td>2</td>
<td>–</td>
<td>ms</td>
</tr>
<tr>
<td>Fault Mode Output Voltage (Fault State)</td>
<td>$V_{OUT(FAULT)}$</td>
<td>$V_{PU} = V_{CC}, \tau &lt; 3 , \mu\text{s}$,[5], $I_{OUT} &lt; 12 , \text{mA}$</td>
<td>$V_{PU} &gt; V_{OUT(HIGH)MAX}$</td>
<td>$V_{PU}$</td>
<td>–</td>
<td>V</td>
</tr>
<tr>
<td>Overtemperature Shutdown</td>
<td>$T_{SD}$</td>
<td>Temperature increasing</td>
<td>–</td>
<td>205</td>
<td>–</td>
<td>$^\circ\text{C}$</td>
</tr>
<tr>
<td>Overtemperature Hysteresis</td>
<td>$T_{JHYS}$</td>
<td></td>
<td>–</td>
<td>25</td>
<td>–</td>
<td>$^\circ\text{C}$</td>
</tr>
</tbody>
</table>

[1] Typical data is at $T_A = 25^\circ C$ and $V_{CC} = 12 \, \text{V}$ and is for design information only.

[2] $V_{CC}$ represents the voltage between the VCC pin and the GND pin.

[3] Power-On Time ($t_{\text{ON}}$) is measured from $V_{CC} = V_{CC}(\text{min})$ to 50% of the output transition from $V_{PU}$ to final value. Adding a bypass capacitor will increase Power-On Time.

[4] The overshoot specification pertains only to conditions where the overshoot is greater than the $V_{OUT(HIGH)MAX}$ specification.

[5] $\tau$ is the time constant of the RC circuit; $\tau = R_{PU} \times C_{OUT}$.

[6] The diagnostics fault retry repeats continuously until a fault condition is no longer observed. See Diagnostics Mode Operation section for details.

TRANSIENT PROTECTION CHARACTERISTICS: Valid for $T_A = 25^\circ C$ and $C_{\text{BYP}} = 0.1 \, \text{µF}$, unless otherwise specified.

<table>
<thead>
<tr>
<th>Characteristics</th>
<th>Symbol</th>
<th>Test Conditions</th>
<th>Min.</th>
<th>Typ.</th>
<th>Max.</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>PROTECTION</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Forward Supply Zener Clamp Voltage</td>
<td>$V_Z$</td>
<td>$I_{CC(max)} + 3 , \text{mA}$</td>
<td>35</td>
<td>–</td>
<td>–</td>
<td>V</td>
</tr>
<tr>
<td>Reverse Supply Zener Clamp Voltage</td>
<td>$V_{RCC}$</td>
<td>$I_{CC} = -1 , \text{mA}$</td>
<td>–</td>
<td>–</td>
<td>–30</td>
<td>V</td>
</tr>
<tr>
<td>Reverse Supply Current</td>
<td>$I_{RCC}$</td>
<td>$V_{RCC} = -30 , \text{V}$</td>
<td>–</td>
<td>–</td>
<td>–5</td>
<td>mA</td>
</tr>
</tbody>
</table>
MAGNETIC CHARACTERISTICS: Valid over full operating voltage and ambient temperature ranges for $T_J < T_J(\text{max})$, unless otherwise specified

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Sensitivity Temperature Coefficient</td>
<td>$T_{\text{CSENS}}$</td>
<td>Relative to sensitivity at 25°C</td>
<td>(A) Flat</td>
<td>–</td>
<td>0</td>
<td>–</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>(B) SmCo</td>
<td>–</td>
<td>–0.035</td>
<td>–</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>(C) NdFeB</td>
<td>–</td>
<td>–0.12</td>
<td>–</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>(D) Ferrite</td>
<td>–</td>
<td>–0.2</td>
<td>–</td>
</tr>
<tr>
<td>Analog Signal Bandwidth</td>
<td>$f_{(-3dB)}$</td>
<td>–</td>
<td>10</td>
<td>–</td>
<td>kHz</td>
<td></td>
</tr>
<tr>
<td>Operate Point</td>
<td>$B_{\text{OP}}$</td>
<td>APS12450–0SxA</td>
<td>5</td>
<td>22</td>
<td>40</td>
<td>G</td>
</tr>
<tr>
<td></td>
<td></td>
<td>APS12450–1SxA</td>
<td>15</td>
<td>50</td>
<td>90</td>
<td>G</td>
</tr>
<tr>
<td></td>
<td></td>
<td>APS12450–3SxA</td>
<td>100</td>
<td>150</td>
<td>180</td>
<td>G</td>
</tr>
<tr>
<td>Release Point</td>
<td>$B_{\text{RP}}$</td>
<td>APS12450–0SxA</td>
<td>–40</td>
<td>–22</td>
<td>–5</td>
<td>G</td>
</tr>
<tr>
<td></td>
<td></td>
<td>APS12450–1SxA</td>
<td>–90</td>
<td>–50</td>
<td>–15</td>
<td>G</td>
</tr>
<tr>
<td></td>
<td></td>
<td>APS12450–3SxA</td>
<td>–180</td>
<td>–150</td>
<td>–100</td>
<td>G</td>
</tr>
<tr>
<td>Hysteresis</td>
<td>$B_{\text{HYS}}$</td>
<td>APS12450–0SxA</td>
<td>10</td>
<td>45</td>
<td>80</td>
<td>G</td>
</tr>
<tr>
<td></td>
<td></td>
<td>APS12450–1SxA</td>
<td>30</td>
<td>100</td>
<td>180</td>
<td>G</td>
</tr>
<tr>
<td></td>
<td></td>
<td>APS12450–3SxA</td>
<td>200</td>
<td>300</td>
<td>360</td>
<td>G</td>
</tr>
<tr>
<td>Symmetry</td>
<td>$B_{\text{SYM}}$</td>
<td>$B_{\text{OP}} + B_{\text{RP}}$</td>
<td>–30</td>
<td>–</td>
<td>30</td>
<td>G</td>
</tr>
<tr>
<td>Jitter [3]</td>
<td>–</td>
<td>$B_{\text{OP}} = 22$ G, $B = 100$ G PK-PK, 1000 Hz</td>
<td>–</td>
<td>0.25</td>
<td>–</td>
<td>%</td>
</tr>
</tbody>
</table>

[1] Typical data is at $T_A = 25°C$ and $V_{\text{CC}} = 12$ V, unless otherwise noted; for design information only.

[2] 1 G (gauss) = 0.1 mT (millitesla).

[3] Output edge repeatability as a percentage of the period.

THERMAL CHARACTERISTICS: May require derating at maximum conditions; see application information

<table>
<thead>
<tr>
<th>Characteristic</th>
<th>Symbol</th>
<th>Test Conditions*</th>
<th>Value</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>Package Thermal Resistance</td>
<td>$R_{\text{JIA}}$</td>
<td>Package LH, on 1-layer PCB based on JEDEC standard</td>
<td>228</td>
<td>°C/W</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Package LH, on 2-layer PCB with 0.463 in.$^2$ of copper area each side</td>
<td>110</td>
<td>°C/W</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Package UA, on 1-layer PCB with copper limited to solder pads</td>
<td>165</td>
<td>°C/W</td>
</tr>
</tbody>
</table>

*Additional thermal information available on the Allegro website.
CHARACTERISTIC PERFORMANCE DATA

- **$V_{OUT(HIGH)}$ vs. $T_A$**
- **$V_{OUT(HIGH)}$ vs. $V_{CC}$**
- **$V_{OUT(LOW)}$ vs. $T_A$**
- **$V_{OUT(LOW)}$ vs. $V_{CC}$**
- **$t_{DIAG}$ vs. $T_A$**
- **$t_{DIAG}$ vs. $V_{CC}$**
CHARACTERISTIC PERFORMANCE DATA (continued)

- $I_{CC}$ vs. $T_A$

- $I_{CC}$ vs. $V_{CC}$

- $t_{on}$ vs. $T_A$

- $t_{RISE}$ & $t_{FALL}$ vs. $T_A$
CHARACTERISTIC PERFORMANCE DATA
APS12450–0SxA

- $B_{\text{ROP}}$ vs. $T_A$ and $V_{CC}$
- $B_{\text{HYS}}$ vs. $T_A$ and $V_{CC}$
- $B_{\text{SYM}}$ vs. $T_A$ and $V_{CC}$

Magnetic Flux Density, $B$ vs. Temperature, $T_A$, and Supply Voltage, $V_{CC}$
CHARACTERISTIC PERFORMANCE DATA
APS12450–3SxA

B_{OP3S_A} vs. T_A

B_{OP3S_A} vs. V_{CC}

B_{RP3S_A} vs. T_A

B_{RP3S_A} vs. V_{CC}

B_{HYS3S_A} vs. T_A

B_{HYS3S_A} vs. V_{CC}

B_{SYM3S_A} vs. T_A

B_{SYM3S_A} vs. V_{CC}
FUNCTIONAL DESCRIPTION

Operation

The output of these devices switches when a magnetic field perpendicular to the Hall-effect sensor exceeds the operate point threshold \( B_{\text{OP}} \). When the magnetic field is reduced below the release point \( B_{\text{RP}} \), the device output switches to the alternate state. The output state (polarity) and magnetic field polarity depends on the selected device options. The device is a latch, therefore \( B_{\text{OP}} \) and \( B_{\text{RP}} \) will be in opposite magnetic field polarities.

The difference between operate (\( B_{\text{OP}} \)) and release (\( B_{\text{RP}} \)) points is the hysteresis (\( B_{\text{HYS}} \)). Hysteresis allows clean switching of the output even in the presence of external mechanical vibration and electrical noise. The hysteresis is set to double the programmed operating point.

Figure 1 shows the output switching behavior relative to increasing and decreasing magnetic field. On the horizontal axis, the \( B^+ \) direction indicates increasing south polarity magnetic field strength. Figure 2 shows the sensing orientation of the magnetic field, relative to the device package.

Note that this device "latches"; that is, a south pole of sufficient strength towards the branded face of the device turns the device on, and the device remains on with removal of the south pole.

Figure 1 shows the potential unipolar and omnipolar options and output polarity options of the APS12450 that can be configured. The direction of the applied magnetic field is perpendicular to the branded face of the APS12450 (see Figure 2).

Figure 1: Hall latch magnetic and output polarity options

- \( B^- \) indicates increasing north polarity magnetic field strength, and
- \( B^+ \) indicates increasing south polarity magnetic field strength.

Figure 2: Magnetic Sensing Orientations

APS12450 LH (Panel A), APS12450 UA (Panel B)
**FUNCTIONAL SAFETY**

The APS12450 was developed in accordance with ISO 26262:2011 as a hardware safety element out of context with ASIL B capability (pending assessment) for use in automotive safety-related systems when integrated and used in the manner prescribed in the applicable safety manual and datasheet.

**Diagnostics Mode Operation**

The APS12450 features a proprietary diagnostics routine that meets ASIL B safety requirements (pending assessment). This internal diagnostics routine continuously runs in the background, monitoring all key subsystems of the IC. These subsystems are shown in Table 1 and Figure 3. The diagnostic scheme runs at high speed and provides minimal impact on device performance. Signal path diagnostics are injected and measured in less than 2 μs, while all other diagnostics are running in real time in the background. The Hall element biasing circuit and voltage regulator are checked for valid operation, and the digital and non-volatile memory blocks are checked for valid device configuration.

The signal path monitoring system verifies two internal state transitions ($B_{OP}$ and $B_{RP}$ within limits) under normal operation. In cases when these output transitions do not occur, or if another internal fault is detected, the output will go to the fault state (see “Three-Wire Diagnostic Output” section).

In the event of an internal fault, the device will continuously run the diagnostics routine every 2 ms ($t_{DIAGF}$). The periodic recovery attempt sequence allows the device to continually check for the presence of a fault and return to normal operation if the fault condition clears.

In the case where the fault is no longer present, the output will resume normal operation. However, if the fault is persistent, the device will not exit fault mode and the output voltage will continue to be $V_{OUT(FAULT)}$.

When a system rating higher than ASIL B is required, additional external safety measures may be employed (e.g., sensor redundancy and rationality checks, etc.). Refer to the device safety manual for additional details about the diagnostics.

<table>
<thead>
<tr>
<th>Feature</th>
<th>Coverage</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 Hall plate</td>
<td>Connectivity and biasing of Hall plate</td>
</tr>
<tr>
<td>2 Signal path</td>
<td>Signal path and Schmitt trigger</td>
</tr>
<tr>
<td>3 Voltage regulator</td>
<td>Regulator voltage for normal operation</td>
</tr>
<tr>
<td>4 Digital subsystem</td>
<td>Digital subsystem and non-volatile memory</td>
</tr>
<tr>
<td>5 Entire system</td>
<td>Overtemperature and redundancies for single point failures</td>
</tr>
<tr>
<td>6 Output</td>
<td>Output verified through valid regulations states (external monitor)</td>
</tr>
</tbody>
</table>

**Figure 3: Diagnostics Coverage Block Diagram**
Power-On Behavior

During Power-on, the output voltage is in the fault state ($V_{OUT(FAULT)}$), which is the pull-up voltage ($V_{PU}$), until the device is ready to respond appropriately to the input magnetic field ($t > t_{ON}$). If the device powers-on with the field within the hysteresis band, the output will switch from $V_{OUT(FAULT)}$ to the off state ($V_{OUT(HIGH)}$) with standard output polarity as shown in Figure 4. For inverted output polarity operation, the output will switch from $V_{OUT(FAULT)}$ to $V_{OUT(LOW)}$ (not shown).

Temperature Coefficient and Magnet Selection

The APS12450 allows the user to select the magnetic temperature coefficient to compensate for drifts of SmCo, NdFeB, and ferrite magnets over temperature, as indicated in the Magnetic Characteristics specifications table. This compensation improves the magnetic system performance over the entire temperature range. For example, the magnetic field strength from NdFeB decreases as the temperature increases from 25°C to 150°C. This lower magnetic field strength means that a lower switching threshold is required to maintain switching at the same distance from the magnet to the sensor. Correspondingly, higher switching thresholds are required at cold temperatures, as low as −40°C, due to the higher magnetic field strength from the NdFeB magnet. The APS12450 compensates the switching thresholds over temperature as described above. It is recommended that system designers evaluate their magnetic circuit over the expected operating temperature range to ensure the magnetic switching requirements are met.

A sample calculation is provided in the “Applications Information” section.
Three-Wire Diagnostic Output

Three-wire diagnostic output enables the user to identify various fault conditions external to the IC, in addition to the internal fault detection. The output low ($V_{\text{OUT(LOW)}}$) and high ($V_{\text{OUT(HIGH)}}$) states are ratiometric to the pull-up voltage, with low and high states being 20% and 80% respectively. For example, a $V_{\text{CC}}$ and $V_{\text{PULL-UP}}$ of 5 V, the output state levels will be 1.0 V and 4.0 V ±0.5 V. The output RC time constant ($\tau$) must be less than 3 µs (e.g., $R_{\text{PU}} = 3 \, \text{k}\Omega$ and $C_{\text{OUT}} = 1 \, \text{nF}$), and $V_{\text{PU}}$ must be equal to $V_{\text{CC}}$ (recommend pulling up $V_{\text{OUT}}$ directly to $V_{\text{CC}}$).

Under normal operation (Figure 5), the output switches between the $V_{\text{OUT(LOW)}}$ (20%) and $V_{\text{OUT(HIGH)}}$ (80%) states.

With various opens and shorts on any of the IC pins, the output will no longer be controlled by the IC. The output itself may continue to switch, depending on the external connectivity fault; however, the output level(s) observed will deviate from the 20% and 80% (of $V_{\text{PU}}$) output levels.

If an internal fault is detected via diagnostics monitoring, the output will be set to the fault state, $V_{\text{OUT(FAULT)}}$, which is equal to the pull-up voltage, $V_{\text{PU}}$.

Any output voltage levels outside of the valid $V_{\text{OUT(HIGH)}}$ and $V_{\text{OUT(LOW)}}$ ranges indicates a fault as shown in Figure 6. The observed voltage on $V_{\text{OUT}}$ relative to potential fault conditions are summarized in Table 2.

The output relative to the fault condition is summarized in Table 2 below.

<table>
<thead>
<tr>
<th>Fault</th>
<th>Output Level</th>
</tr>
</thead>
<tbody>
<tr>
<td>No Fault</td>
<td>20% or 80% of $V_{\text{PU}}$, respectively</td>
</tr>
<tr>
<td>Short, VCC-VOUT</td>
<td>$V_{\text{CC}}$</td>
</tr>
<tr>
<td>Short, VOUT-GND</td>
<td>$GND$</td>
</tr>
<tr>
<td>Short, VCC-GND</td>
<td>$V_{\text{PU}}$</td>
</tr>
<tr>
<td>Open, VCC</td>
<td>$V_{\text{PU}}$</td>
</tr>
<tr>
<td>Open, VOUT</td>
<td>$V_{\text{PU}}$</td>
</tr>
<tr>
<td>Open, GND</td>
<td>$V_{\text{PU}}$</td>
</tr>
<tr>
<td>Internal Fault</td>
<td>$V_{\text{PU}}$</td>
</tr>
</tbody>
</table>

Note: $V_{\text{OUT(FAULT)}} \leq V_{\text{PULL-UP}}$ and $V_{\text{PULL-UP}} = V_{\text{CC}}$.
Fault Detection and Retry

The fault detection diagnostics runs continuously in the background during normal operation after the device has powered-on. In the event a fault is detected, the output will immediately change to the $V_{\text{OUT(FAULT)}}$ state. The diagnostics will continue to retry the diagnostics approximately every 2 ms. If the fault recovers, the output will return to normal operation. See Figure 7.

Output Overshoot

When the output switches from $V_{\text{OUT(LOW)}}$ to $V_{\text{OUT(HIGH)}}$, depending upon the RC circuit, a small overshoot can occur ($V_{\text{OUT(OVER)}}$). $V_{\text{OUT(OVER)}}$ is specified as a percentage of $V_{\text{PULL-UP}}$ (and/or $V_{\text{CC}}$, which need to be the same). Therefore with an RC Time Constant ($\tau$) of 3 $\mu$s (see the “Applications Information” section), a nominal overshoot of 2% is possible. With $V_{\text{PULL-UP}}$ at 5.0 V, the output may overshoot by 0.1 V, for less than 5 $\mu$s ($t_{\text{OUT(OVER)}}$). Figure 7 demonstrates output edge profile.

For example, with a 5 V pull-up, if $V_{\text{OUT(HIGH)}}$ is at the upper limit (90%), $V_{\text{OUT(HIGH)}}$ will be 4.5 V. With a $\tau$ of 3 $\mu$s at room temperature, the output can briefly reach 4.6 V until it settles to 4.5 V. Since $V_{\text{OUT(HIGH)}}$ is valid between 70% and 90%, or 3.5 and 4.5 V, this condition is not out of specification. The Output Off Voltage Overshoot specification pertains only to conditions where the overshoot is greater than the $V_{\text{OUT(HIGH)MAX}}$ specification.

Figure 7: Fault Detection and Retry

Figure 8: Output Overshoot
Typical Applications

For the LH and UA packages, an external bypass capacitor, \( C_{\text{BYP}} \), should be connected (in close proximity to the Hall sensor) between the supply and ground of the device to reduce both external noise and noise generated by the chopper stabilization technique. As is shown in Figure 9, a 0.1 \( \mu \text{F} \) bypass capacitor is typical, with an optional output capacitor, \( C_{\text{OUT}} \) (recommended 1 nF).

The time constant of the RC circuit (\( \tau \)) on output must be less than 3 \( \mu \text{s} \), where:

\[
\tau = R_{\text{PULLUP}} \times C_{\text{OUT}}
\]

\( = 3 \text{ k}\Omega \times 1 \text{nF} \)

\( = 3 \mu\text{s} \)

The resistor, \( R_{\text{PULLUP}} \), must be between 2 and 30 k\( \Omega \).

Temperature Compensation

To calculate the typical effect of the \( T_{\text{SENS}} \) on \( B_{\text{OP}} \) (or \( B_{\text{RP}} \)), simply multiply the \( B_{\text{OP}} \) at the starting temperature by \( T_{\text{SENS}} \) and the change in temperature.

Sample \( B_{\text{OP}} \) calculation for \( T_{\text{SENS}} \) compensation from 25°C to 150°C, for \( T_{\text{SENS}} = -0.12\%/°\text{C} \), and \( B_{\text{OP}(25°C)} = 180 \text{ G} \):

\[
\Delta T_A = 150°C - 25°C = 125°C
\]

\[
B_{\text{OP}(150°C)} = B_{\text{OP}(25°C)} + (B_{\text{OP}(25°C)} \times T_{\text{SENS}} \times \Delta T_A )
\]

\[
= 180 \text{ G} + (180 \text{ G} \times -0.12\%/°\text{C} \times 125°C)
\]

\[
= 180 \text{ G} + (–27 \text{ G})
\]

\[
= 153 \text{ G}
\]

APPLICATIONS INFORMATION

Figure 9: Typical Applications Circuits

Diagnostic Output

| \( V_{\text{CC}} \) | 3 to 30 V |
| \( V_{\text{PU}} \) | \( V_{\text{CC}} \) |
| \( C_{\text{BYP}} \) | 0.1 \( \mu \text{F} \) |
| \( C_{\text{OUT}} \) | \( \tau \) \( \text{RC} \leq 3 \mu\text{s} \) |
| \( R_{\text{PU}} \) | \( I_{\text{OUT}} < 12 \text{ mA} \) |
| \( \tau \) \( \text{RC} \leq 3 \mu\text{s} \) |
| \( R_S \) | 2 k\( \Omega \) < \( R < 30 \text{k}\Omega \) |
| \( R_S \) | 100 \( \Omega \)* |

* The following application circuit conditions are required
  - The \( \tau \) of the RC on output must be < 3 \( \mu \text{s} \).
  - 2 k\( \Omega \) < \( R_{\text{RC}} \) < 30 k\( \Omega \).
  - \( V_{\text{PU}} = V_{\text{CC}} \) (recommend pulling VOUT up to VCC).
Extensive applications information on magnets and Hall-effect sensors is available in:

- *Hall-Effect IC Applications Guide*, AN27701
- *Guidelines For Designing Subassemblies Using Hall-Effect Devices*, AN27703.1
- *Soldering Methods for Allegro’s Products – SMT and Through-Hole*, AN26009

All are provided on the Allegro website:

[www.allegromicro.com](http://www.allegromicro.com)
Chopper Stabilization Technique

A limiting factor for switchpoint accuracy when using Hall-effect technology is the small-signal voltage developed across the Hall plate. This voltage is proportionally small relative to the offset that can be produced at the output of the Hall sensor. This makes it difficult to process the signal and maintain an accurate, reliable output over the specified temperature and voltage range. Chopper stabilization is a proven approach used to minimize Hall offset.

The technique, dynamic quadrature offset cancellation, removes key sources of the output drift induced by temperature and package stress. This offset reduction technique is based on a signal modulation-demodulation process. “Figure 10: Model of Chopper Stabilization Circuit (Dynamic Offset Cancellation)” illustrates how it is implemented.

The undesired offset signal is separated from the magnetically induced signal in the frequency domain through modulation. The subsequent demodulation acts as a modulation process for the offset causing the magnetically induced signal to recover its original spectrum at baseband while the DC offset becomes a high-frequency signal. Then, using a low-pass filter, the signal passes while the modulated DC offset is suppressed. Allegro’s innovative chopper-stabilization technique uses a high-frequency clock.

The high-frequency operation allows a greater sampling rate that produces higher accuracy, reduced jitter, and faster signal processing. Additionally, filtering is more effective and results in a lower noise analog signal at the sensor output. Devices such as the APS12450 that use this approach have an extremely stable quiescent Hall output voltage, are immune to thermal stress, and have precise recoverability after temperature cycling. This technique is made possible through the use of a BiCMOS process which allows the use of low offset and low noise amplifiers in combination with high-density logic and sample-and-hold circuits.

Figure 10: Model of Chopper Stabilization Circuit (Dynamic Offset Cancellation)
POWER DERATING

The device must be operated below the maximum junction temperature, $T_J$ (max). Reliable operation may require derating supplied power and/or improving the heat dissipation properties of the application.

Thermal Resistance (junction to ambient), $R_{\text{thJA}}$, is a figure of merit summarizing the ability of the application and the device to dissipate heat from the junction (die), through all paths to ambient air. $R_{\text{thJA}}$ is dominated by the Effective Thermal Conductivity, $K$, of the printed circuit board which includes adjacent devices and board layout. Thermal resistance from the die junction to case, $R_{\text{thJC}}$, is a relatively small component of $R_{\text{thJA}}$. Ambient air temperature, $T_A$, and air motion are significant external factors in determining a reliable thermal operating point.

The following three equations can be used to determine operation points for given power and thermal conditions.

\[ P_D = V_{IN} \times I_{IN} \]  
\[ \Delta T = P_D \times R_{\text{thJA}} \]  
\[ T_J = T_A + \Delta T \]

For example, given common conditions: $T_A = 25^\circ C$, $V_{CC} = 12$ V, $I_{CC} = 4$ mA, and $R_{\text{thJA}} = 110^\circ C/W$ for the LH package, then:

\[ P_D = V_{CC} \times I_{CC} = 12 \text{ V} \times 4 \text{ mA} = 48 \text{ mW} \]
\[ \Delta T = P_D \times R_{\text{thJA}} = 48 \text{ mW} \times 110^\circ C/W = 5.28^\circ C \]
\[ T_J = T_A + \Delta T = 25^\circ C + 5.28^\circ C = 31.28^\circ C \]

Determining Maximum $V_{CC}$

For a given ambient temperature, $T_A$, the maximum allowable power dissipation as a function of $V_{CC}$ can be calculated. $P_D$ (max) represents the maximum allowable power level without exceeding $T_J$ (max) at a selected $R_{\text{thJA}}$ and $T_A$.

Example: $V_{CC}$ at $T_A = 150^\circ C$, package UA, using low-K PCB. Using the worst-case ratings for the device, specifically: $R_{\text{thJA}} = 165^\circ C/W$, $T_J$ (max) = $165^\circ C$, $V_{CC}$ (max) = $24$ V, and $I_{CC}$ (max) = $4$ mA, calculate the maximum allowable power level, $P_D$ (max).

First, using equation 3:

\[ \Delta T (\text{max}) = T_J (\text{max}) - T_A = 165^\circ C - 150^\circ C = 15^\circ C \]

This provides the allowable increase to $T_J$ resulting from internal power dissipation. Then, from equation 2:

\[ P_D (\text{max}) = \Delta T (\text{max}) \times R_{\text{thJA}} = 15^\circ C \times 165^\circ C/W = 91 \text{ mW} \]

Finally, using equation 1, solve for maximum allowable $V_{CC}$ for the given conditions:

\[ V_{CC} (\text{est}) = P_D (\text{max}) \div I_{CC} (\text{max}) = 91 \text{ mW} \div 4 \text{ mA} = 22.8 \text{ V} \]

The result indicates that, at $T_A$, the application and device can dissipate adequate amounts of heat at voltages $\leq V_{CC} (\text{est})$.

If the application requires $V_{CC} > V_{CC\text{(est)}}$ then $R_{\text{thJA}}$ must by improved. This can be accomplished by adjusting the layout, PCB materials, or by controlling the ambient temperature.

Determining Maximum $T_A$

In cases where the $V_{CC}$ (max) level is known, and the system designer would like to determine the maximum allowable ambient temperature $T_A$ (max), for example, in a worst-case scenario with conditions $V_{CC}$ (max) = $40$ V, $I_{CC}$ (max) = $4$ mA, and $R_{\text{thJA}} = 228^\circ C/W$ for the LH package using equation 1, the largest possible amount of dissipated power is:

\[ P_D = V_{IN} \times I_{IN} \]
\[ P_D = 40 \text{ V} \times 4 \text{ mA} = 160 \text{ mW} \]

Then, by rearranging equation 3 and substituting with equation 2:

\[ T_A (\text{max}) = T_J (\text{max}) - \Delta T \]
\[ T_A (\text{max}) = 165^\circ C - (160 \text{ mW} \times 228^\circ C/W) \]
\[ T_A (\text{max}) = 165^\circ C - 36.5^\circ C = 128.5^\circ C \]

In another example, the maximum supply voltage is equal to $V_{CC}$ (min). Therefore, $V_{CC}$ (max) = $3$ V and $I_{CC}$ (max) = $4$ mA. By using equation 1 the largest possible amount of dissipated power is:

\[ P_D = V_{IN} \times I_{IN} \]
\[ P_D = 3 \text{ V} \times 4 \text{ mA} = 12 \text{ mW} \]

Then, by rearranging equation 3 and substituting with equation 2:

\[ T_A (\text{max}) = T_J (\text{max}) - \Delta T \]
\[ T_A (\text{max}) = 165^\circ C - (12 \text{ mW} \times 228^\circ C/W) \]
\[ T_A (\text{max}) = 165^\circ C - 11.6^\circ C = 162.3^\circ C \]

The example above indicates that at $V_{CC} = 3$ V and $I_{CC} = 4$ mA, the $T_A$ (max) can be as high as $162.3^\circ C$ without exceeding $T_J$ (max). However the $T_A$ (max) rating of the device is $150^\circ C$; the device performance is not guaranteed above $T_A = 150^\circ C$. 

For example, given common conditions: $T_A = 25^\circ C$, $V_{CC} = 12$ V, $I_{CC} = 4$ mA, and $R_{\text{thJA}} = 110^\circ C/W$ for the LH package, then:

\[ P_D = V_{CC} \times I_{CC} = 12 \text{ V} \times 4 \text{ mA} = 48 \text{ mW} \]
\[ \Delta T = P_D \times R_{\text{thJA}} = 48 \text{ mW} \times 110^\circ C/W = 5.28^\circ C \]
\[ T_J = T_A + \Delta T = 25^\circ C + 5.28^\circ C = 31.28^\circ C \]
Package LH, 3-Pin SOT23W

For reference only; not for tooling use (reference DWG-0000628, Rev. 1). Dimensions in millimeters. Dimensions exclusive of mold flash, gate burns, and dambar protrusions. Exact case and lead configuration at supplier discretion within limits shown.

Active Area Depth: 0.28 ±0.04 mm
Reference land pattern layout
All pads a minimum of 0.20 mm from all adjacent pads; adjust as necessary to meet application process requirements and PCB layout tolerances
Branding scale and appearance at supplier discretion
Hall element, not to scale
Package UA, 3-Pin SIP, Matrix HD Style

For reference only; not for tooling use (reference DWG-0000404, Rev. 1).
Dimensions in millimeters.
Dimensions exclusive of mold flash, gate burrs, and dambar protrusions. Exact case and lead configuration at supplier discretion within limits shown.

- Dambar removal protrusion (6x)
- Gate and tie bar burr area
- Active Area Depth, 0.50 ±0.08 mm
- Branding scale and appearance at supplier discretion
- Hall element (not to scale)
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