

# ENHANCING ROBOTIC DESIGN

High precision, maximum efficiency, and increased reliability

Industrial robotics has transformed the way we live and operate. From assembling and distributing company products more efficiently to creating a safe environment for medical and military practices, robotics play a vital role in our everyday lives. With the continuously evolving robotic market and formation of new applications, there is a need for higher levels of system accuracy and reliability.

The key component to many robotic systems is motion control. Many of the motors used in robotic applications require solutions that can support high speed and precision, maximize motor efficiency, and simplify design all while maintaining long-term performance.

Allegro's broad selection of sensor and power ICs help design high performance and resilient systems by creating more accurate and high bandwidth control of position, torque, and speed. These highly integrated solutions simplify motor design while achieving smoother and more efficient motor control. Leveraging its expertise in the automotive market, Allegro's offerings have built-in protections, on-chip diagnostics, and redundant options to support industrial safety standards for a more robust and reliable system.



## What you can achieve with Allegro solutions

### Speed and Precision

Design high performance systems with accurate and high bandwidth control of position, torque, and speed.

### Safety and Reliability

Achieve industrial functional safety standards for a more robust and reliable system.

### Simplification and Efficiency

Streamline system design and deliver more efficient motor control with highly integrated solutions.

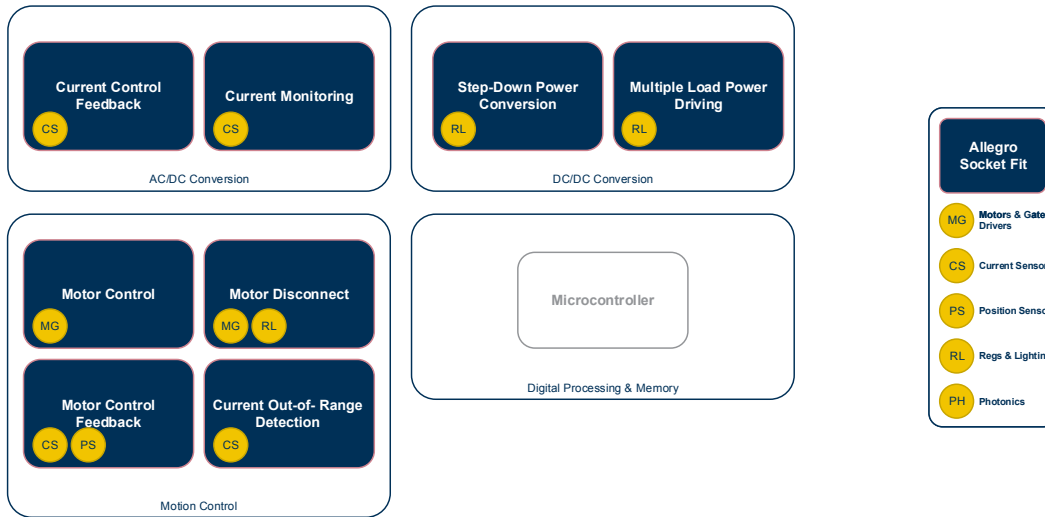


- 1 Battery Management
- 2 Motor Control & Feedback
- 3 Bumper Detection
- 4 Lifting
- 5 Illumination



# Market-Leading Portfolios That Sense, Regulate, and Drive

## Simple Block Diagram



## Features and Benefits

Subsystem	Component	Allegro Part
AC/DC Conversion	Current Control Feedback	<a href="#">ACS71240, ACS37010</a>
	Current Monitoring	<a href="#">ACS71240</a>
DC/DC Conversion	Step-Down Power Conversion	<a href="#">A4447, A4490/1, A8498</a>
	Multiple Load Power Driving	<a href="#">A81407, ARG82800/1, ARG81403</a>
Motion Control	Current Out-of-Range Detection	<a href="#">ACS712140, ACS730</a>
	Motor Control Feedback (current)	<a href="#">ACS71240, ACS37010</a>
BLDC Motor	Motor Control	<a href="#">A89306, AMT49406, AMT49413</a>
	Motor Disconnect	<a href="#">A6861, A81407, ARG82800/1/1-1</a>
	Motor Control Feedback (commutation)	<a href="#">APS12202, APS12215, A1220</a>
	Motor Control Feedback (angle)	<a href="#">AAS33001, A33230</a>
Brushed DC Motor	Motor Control	<a href="#">AMT49701, A89500/5/6, A3908</a>
	Motor Control Feedback (speed/direction)	<a href="#">APS12625/6</a>
Stepper Motor	Motor Control	<a href="#">AMT49700</a>
	Motor Control Feedback (proximity)	<a href="#">APS11202</a>
	Motor Control Feedback (angle)	<a href="#">A1333</a>
Servo Motor	Motor Control Feedback (rotary encoder)	<a href="#">A1335/9, ALS31300</a>
	Motor Control Feedback (linear encoder)	<a href="#">A31315, ALS31300</a>



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