

FEATURES AND BENEFITS

- · AEC-Q100 qualified
- $V_{\rm IN}$ range: 5.3 to 40 V supply, operates down to 5.1 V when enabled
- Four independent MOSFET drivers
- Internal and external PWM dimming options
 - Internal PWM dimming set by resistor divider or analog voltage
 - External PWM dimming set by microcontroller
- Flexible LED analog dimming options
 - Two ADIM pins for LED binning, NTC feedback, or hybrid analog/PWM dimming
 - Adjustable integrated LED current derating for elevated V_{IN}
 - Integrated LED current derating for elevated IC junction temperature
- Combine A80804 devices in parallel for higher number of LED strings; PWMOUT signal available when used with internal PWM for controller/peripheral operation
- MINOUT signal available to trim a pre-regulator to minimize power loss
- Selectable LED current slew rate limit during PWM dimming
- Extensive fault detection and protection
 - · Drain short-to-ground detection
 - Drain short-to-VIN
 - Open LED
 - Thermal protection
 - Programmable input UVLO

DESCRIPTION

The A80804 and A80804-1 are linear, programmable current controllers capable of accurately regulating current in four LED strings using external MOSFETs. Each of the four LED drivers has an independent enable/PWM input and current-sense resistors and can be independently dimmed with an external PWM signal, or all channels can be dimmed with internal PWM dimming and automatic phase shifting. The overall LED current can be switched between low and full intensity for applications including stop/tail or DRL/position lighting. Multiple analog dimming options are available to support applications including LED binning, NTC foldback, or hybrid dimming. A selectable LED current slew-rate control is available to tune PWM edge times and improve EMI performance.

The MINOUT feature allows for trimming an external DC-DC converter to optimize the voltage across the linear current regulating MOSFETs to minimize power loss.

The A80804 offers several fault detection and protection options including MOSFET drain short-to-ground, drain short-to-VIN, open-LED fault protection, internal overtemperature protection, and undervoltage lockout. The A80804 can be configured for either one-out-all-out or one-out-continue operation.

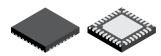
The A80804 has a 500 mV current-sense reference for improved BCI performance. The A80804-1 has a 200 mV current-sense reference for lower power dissipation in the sense resistor.

The device is packaged in a 32-pin QFN (ET) with exposed pad for enhanced thermal dissipation and wettable flank construction for solderability and visual inspection.

APPLICATIONS

- Automotive medium-power LED lighting systems
- Fog lights, backup lights, daytime running lights, position lights, sequential light

PACKAGE



32-contact QFN 5 mm × 5 mm × 0.90 mm with exposed thermal pad and wettable flank (suffix ET)

Not to scale

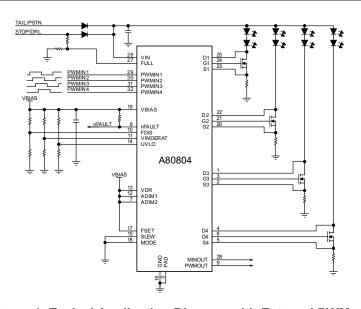


Figure 1: Typical Application Diagram with External PWM

High-Current Four-Channel Automotive LED Controller

SELECTION GUIDE

Part Number	V _{SENSE} Option (mV)	Package	Packing ^[1]
A80804KETASR	500	32-pin 5 mm × 5 mm QFN	6000 pieses per 12 inch reel
A80804KETASR-1	200	with exposed thermal pad and wettable flank	6000 pieces per 13-inch reel

^[1] Contact Allegro for additional packing options.

ABSOLUTE MAXIMUM RATINGS [2]

Characteristic	Symbol	Notes	Rating	Unit
VIN, FULL, nFAULT, PWMINx, Dx, Gx, and MINOUT Pins			-0.3 to 45	V
All other pins			-0.3 to 7	V
Maximum Continuous Junction Temperature	T _{J(MAX)}		150	°C
Transient Junction Temperature	T _J		175	°C
Storage Temperature Range	T _{stg}		-55 to 150	°C

^[2] Stresses beyond those listed in this table may cause permanent damage to the device. The absolute maximum ratings are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the Electrical Characteristics table is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

THERMAL CHARACTERISTICS

Characteristic Symbol		Test Conditions [3]	Value	Unit
Junction to Ambient Thermal Resistance	$R_{\theta JA}$	On 4-layer PCB based on JEDEC standard	30	°C/W

^[3] Additional thermal information available on the Allegro website.

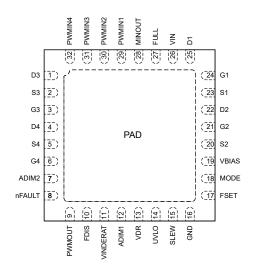
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TERMINAL DIAGRAM AND TERMINAL LIST



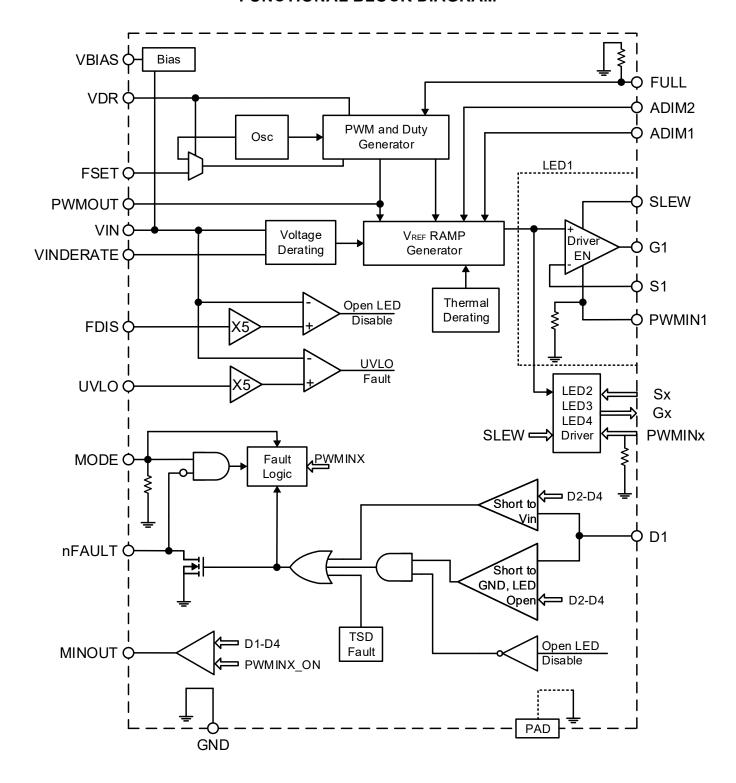
ET-32 Package Terminals

Terminal List

Number	Name	Function
1	D3	Drain sensing for channel 3 for LED fault detection.
2	S3	Current sense for channel 3; connect sense resistor to GND to set peak current level.
3	G3	Gate driver for external N-channel MOSFET for channel 3.
4	D4	Drain sensing for channel 4 for LED fault detection.
5	S4	Current sense for channel 4; connect sense resistor to GND to set peak current level.
6	G4	Gate driver for external N-channel MOSFET for channel 4.
7	ADIM2	Voltage on this pin sets peak LED current. This pin can be used for external thermal derating using an NTC, or "hybrid" analog and PWM dimming to extend the range of PWM duty cycles.
8	nFAULT	Open-drain active low fault flag output; also used as fault input when MODE is connected to VBIAS.
9	PWMOUT	Replicated internal PWM dimming frequency and duty cycle signal for cascaded driver applications. Leave PWMOUT pin open if it is not used. PWMOUT is not driven in external PWM mode.
10	FDIS	VIN threshold for LED Open fault detection.
11	VINDERAT	Voltage at this pin sets VIN derating threshold.
12	ADIM1	Voltage on this pin sets peak LED current. This pin can be used for LED binning adjustment.
13	VDR	Voltage on this pin sets the internal PWM dimming duty cycle.
14	UVLO	Voltage at this pin sets the input voltage UVLO threshold.
15	SLEW	Controls rise and fall times of LED current. Tie to VBIAS to drive LEDs with 80 µs slew time or tie to GND to drive LEDs with 6 µs slew time. Connect a resistor to GND to adjust slew time between this range.
16	GND	Ground.
17	FSET	Sets internal PWM dimming frequency. Connect a resistor to GND to set internal PWM frequency; connect to VBIAS when using external PWM.
18	MODE	Sets the fault handling mode. Tie to VBIAS for "one-out-all-out" or the GND for "one-out-continue". See Table 1.
19	VBIAS	Internal bias supply; connect to GND through a 2.2 μF / 16 V ceramic capacitor. VBIAS pin can deliver up to 10 mA to an external load.
20	S2	Current sense for channel 2; connect sense resistor to GND to set peak current level.
21	G2	Gate driver for external N-channel MOSFET for channel 2.
22	D2	Drain sensing for channel 2 for LED fault detection.
23	S1	Current sense for channel 1; connect sense resistor to GND to set peak current level.
24	G1	Gate driver for external N-channel MOSFET for channel 1.
25	D1	Drain sensing for channel 1 for LED fault detection.
26	VIN	Input supply; place a 0.1 µF decoupling capacitor close to this pin.
27	FULL	Drive high to override PWM settings and force all enabled LED channels to 100% duty cycle; drive low for LEDs to operate in PWM mode. In external PWM mode, if any PWMINx pin is low at startup, the FULL pin must be low for at least 20 ms.
28	MINOUT	Provides minimum drain voltage of enabled channels during LED on-time; use for feedback to adjust the output of a pre-regulator.
29	PWMIN1	External PWM input for LED channel 1; tie this pin high for 100% duty cycle or to use internal dimming.
30	PWMIN2	External PWM input for LED channel 2; tie this pin high for 100% duty cycle or to use internal dimming.
31	PWMIN3	External PWM input for LED channel 3; tie this pin high for 100% duty cycle or to use internal dimming.
32	PWMIN4	External PWM input for LED channel 4; tie this pin high for 100% duty cycle or to use internal dimming.
-	PAD	Exposed thermal pad; connect to external ground pad for better thermal performance.



FUNCTIONAL BLOCK DIAGRAM





High-Current Four-Channel Automotive LED Controller

ELECTRICAL CHARACTERISTICS [1]: Unless otherwise specified, V_{IN} = 12 V. "•" indicates specifications across the full operating temperature range of T_J = -40°C to 150°C; other specifications are at T_J = 25°C, unless noted otherwise. Refer to Figure 23 in application information section for typical application.

Characteristics	Symbol		Test Conditions		Min.	Тур.	Max.	Unit
INPUT SUPPLY								
Operating Input Voltage Range	V _{IN}			•	5.3	-	40	V
V _{IN} Operational Current	I _{INQ}	FULL = HIG	Н	•	-	-	10	mA
Startup Time	t _{ON}	$V_{SX} = 20 \text{ m/s}$	μF, V _{INDERAT} = V _{ADIMx} = V _{BIAS} , ((A80804-1), V _{SX} = 50 mV (A80804), WMINx toggled high.		-	100	-	μs
CURRENT REGULATION				•				
			V _{VINDERAT} = V _{ADIMX} = V _{VBIAS}	•	194	200	206	mV
O. D. farrance Valle and	.,	A80804-1	$V_{VINDERAT} = V_{ADIMX} = V_{VBIAS}$ ($T_J = 125$ °C)		196	200	204	mV
Sx Reference Voltage	V _{SENSE}		V _{VINDERAT} = V _{ADIMx} = V _{VBIAS}	•	485	500	515	mV
		A80804	V _{VINDERAT} = V _{ADIMX} = V _{VBIAS} (T _J = 125°C)		490	500	510	mV
Sx Reference Matching [1]	Err _{VSENSE}	No derating			-	-	2	%
Analog Dimming ADIM1 / VBIAS Ratio	ADIM1R		las, no derating, V (A80804-1), V _{SX} = 450 mV (A80804)		-	0.72	-	_
Analog Dimming ADIM2 / VBIAS Ratio	ADIM2R	V _{ADIM1} = V _{VB} V _{SX} = 180 m ³	las, no derating, V (A80804-1), V _{SX} = 450 mV (A80804)		-	0.45	-	_
VBIAS								
VBIAS Pin Voltage	V _{VBIAS}	I _{VBIAS} = 0 to	10 mA	•	4.85	5.0	5.15	V
VBIAS Undervoltage Release	V _{VBIASUV}	V _{IN} rising			-	4.5	_	V
VBIAS Undervoltage Lockout Hysteresis	V _{VBIASHYS}	IC disabled			-	0.2	-	V
GATE DRIVER								
Gx High-Level Output	V _{GATEH}		Gx High, V _{SX} = 180 mV (A80804-1) 50 mV (A80804)		6	_	9	V
Gx Low-Level Output	V _{GATEL}	FSET = VB	IAS, PWMIN = LOW		-	-	0.7	V
GATE Driver Dropout	V _{GATE_drop}	V _{IN} = 5.3 V, V V _{SX} = 450 m	V_{SX} = 180 mV (A80804-1) and V (A80804), measured as (V _{IN} – V _{GX})		-	_	1	V
Gate Pull-Up Current	I _{GPU}	V _{SX} = 180 m V _{SX} = 450 m	IV (A80804-1) and IV (A80804), V _{GX} = 0 V, V _{IN} = 7 V		-	-360	-	μA
Gate Pull-Down Current	IGPD	V _{SX} = 220 mV (A80804-1) and V _{SX} = 550 mV (A80804), V _{GX} = 7 V, V _{IN} = 7 V			-	360	-	μΑ
External FET Gate Capacitance Range [4]	C _{GISS}	For stable operation		П	250	-	2000	pF
Propagation Delay	t _{pdi}	Delay from Internal PWM and PWMOUT pin during internal PWM mode.			-	2	-	μs
Propagation Delay, External PWM Mode	t _{pde}	Delay from PWMINx pin rising or falling level to Gx rising 3 V; C _{gate} = 1 nF			-	2	-	μs
PWM Matching During External PWM			nismatch at 5%, 200 Hz PWM signal		-	_	6	%
PWM Dimming Frequency	f _{PWM}	R _{FPWM} = 30.	9 kΩ, across FSET to GND	•	180	200	220	Hz

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ELECTRICAL CHARACTERISTICS [1] (continued): Unless otherwise specified, V_{IN} = 12 V. "•" indicates specifications across the full operating temperature range of T_J = -40°C to 150°C; other specifications are at T_J = 25°C, unless noted otherwise. Refer to Figure 23 in application information section for typical application.

Characteristics	Symbol	Test Conditions			Min.	Тур.	Max.	Unit
GATE DRIVER (continued)	•						•	
	_	V _{DR} driven by resistor divider from VBIAS,	$V_{VBIAS} / V_{DR} = 73 V$, SLEW = Low		1	2	3	%
Internal PWM Duty Cycle	D _{PWML}	f _{PWM} = 200 Hz,	V_{VBIAS} / V_{DR} = 29.2 V, SLEW = Low		4.25	5	5.8	%
menar viii Baty Gyole	D _{PWMH}	V _{DR} driven by resistor divider from VBIAS,	SLEW = Low		88	90	92	%
	БРWМН	$V_{VBIAS} / V_{DR} = 1.62 V,$ $f_{PWM} = 200 Hz$	SLEW = High		88	90	92	%
		Rising or falling	SLEW = High		49	80	111	μs
Current Slew Time	t _{SLEW}	between 10% and 90% levels, for internal	SLEW = Low		4	8	12	μs
		reference ramp	R_{SLEW} = 100 k Ω		14	25	36	μs
Dies Tiese to Call Tiese Matakies [2]	_	Rising or falling between for internal PWM; SLEW			-	20	-	μs
Rise Time to Fall Time Matching [2]	t _{SM}	Rising or falling between 10% and 90% levels, for external PWM; SLEW = High			-	20	-	μs
Rise Time and Fall Time Mismatch Between Four Strings [3][4]	t _{SMS}	Rise and fall time mismatch between 10% and 90% levels in four strings; SLEW = High			-	3	-	%
INTERNAL PWM POLYPHASE DELA	Y					•		
Poly-Phase Delay	t _{dpp}	Internal PWM, delay between rise and fall times of successive outputs; measured at 50% V _{SENSE} levels			-	100	-	μs
LOGIC PINS		<u>'</u>						
MODE, SLEW, FSET, PWMINX, nFAULT, FULL Pins, Input Low Voltage	V _{IL}	Below V _{IL} level, input vol logic low	tage considered as	•	0.8	_	1.1	V
MODE, SLEW, FSET, PWMINX, nFAULT, FULL Pins, Input High Voltage	V _{IH}	Above V _{IH} level, input vo	ltage considered as	•	1.5	_	2	V
nFAULT, PWMOUT Pins, Output Low Voltage	V _{OL}	I _{OL} = 1 mA		•	-	_	0.4	V
PWMOUT Pin, Output High Voltage	V _{OH}	I _{OH} = -1 mA		•	4	_	_	V
MODE, PWMINx, FULL, Pin Pull- Down Resistor	R _{in}				-	100	_	kΩ
PROTECTION								
Input Voltage Required to Derate VSENSE by 10%	V _{INth(L)}	V _{INDERAT} = 2 V			19.7	20.7	21.7	V
V_{IN} Derating Range ($V_{INth(H)}$ to $V_{INth(L)}$)	V _{INthd}	V _{SENSE} drops from 90% to 60% level			-	2.16	-	V
Maximum V _{IN} Derating for SENSE Voltage	V _{REF1}	V _{INDERAT} = 2 V, V _{IN} ≥ 26 V			-	50	-	%
VIN-to-Drain Short Detect Voltage	V _{SCV}	Measured as $V_{IN} - V_{Dx}$, $Gx = PWMINx = high$			0.5	0.8	1.1	V
Open LED Fault Detect Voltage	V _{OLED}	Measured at Dx, V _{IN} > 5 × V _{FDSET}			0.19	0.24	0.29	V
Open LED Disable Input Voltage	V _{FDIS_VIN}	V _{FDIS} = 2 V			_	10	-	V

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High-Current Four-Channel Automotive LED Controller

ELECTRICAL CHARACTERISTICS [1] (continued): Unless otherwise specified, V_{IN} = 12 V. "•" indicates specifications across the full operating temperature range of T_J = -40°C to 150°C; other specifications are at T_J = 25°C, unless noted otherwise. Refer to Figure 23 in application information section for typical application.

Characteristics	Symbol	Test Conditions	Min.	Тур.	Max.	Unit			
PROTECTION (continued)									
PWM Frequency In Case Of Fault On Faulty Channel (FULL and External PWM Mode)	_	Open LED or Short to Drain fault	_	500	-	Hz			
PWM Duty Cycle In Case Of Fault On Faulty Channel	_		-	5	-	%			
Fault Detection Time (FULL Mode)	-	Open LED or Short to Drain fault	_	6	-	ms			
Fault Detection Cycles (PWM Mode)	-		_	3	-	cycles			
Fault reset time (FULL or External PWM)	_		-	20	-	ms			
Input Under Voltage Detect Voltage	V _{UVLO}	V _{UVLO} = 2 V, V _{IN} Falling (5×)	-	10	-	V			
Input Under Voltage Detect Voltage Hysteresis	V _{UVLOhys}	V _{IN} rising (fixed)	-	0.8	-	V			
Thermal Monitor Activation Temperature [4]	T _{JM}	T _J at V _{SENSE} = 180 mV (A80804-1) and V _{SENSE} = 450 mV (A80804)	-	T _{JF} – 21	-	°C			
Thermal Monitor Low Current Temperature [4]	T _{JL}	T_J at V_{SENSE} = 70 mV (A80804-1) and V_{SENSE} = 175 mV (for A80804)	-	T _{JF} – 7	_	°C			
Overtemperature Shutdown [4]	T _{JF}	Temperature increasing	-	170	-	°C			
Overtemperature Hysteresis [4]	T _{Jhys}	Recovery = T _{JF} – T _{Jhys}	-	30	-	°C			
MINOUT									
MINOUT Internal Reference Voltage	V _{MINOUT}		-	0.8	-	V			
MINOUT Drive Capability I _{MINOUT}			-	±100	-	μA			
MINOUT Gain A _{MINOUT}			_	10	-	-			
MIONOUT Offset	V _{NIMOUT_off}		_	0.5	-	V			

^[1] Reference matching is defined as: $(V_{SENSEmax} - V_{SENSEmin}) / V_{SENSE(AVG)}$, where $V_{SENSE(AVG)}$ is the average of all enabled V_{SENSEx} . [2] Rise Time to Fall Time Matching is defined as the maximum difference between the rise time and the fall time of the same string.



^[3] Rise Time to Fall Time Mismatch Between Four Strings is defined as the maximum ratio of the difference between either the rise time or the fall time to the average of the rise time or fall times between four strings.

^[4] Ensured by design and characterization.

FUNCTIONAL DESCRIPTION

The A80804 is a four-channel linear current regulator for LED driver applications using external N-channel MOSFETs to handle power dissipation in linear mode. The LED current in each channel can be programmed separately by selecting each current-sense resistor. Each channel also has a separate PWMINx pin to control external PWM dimming or act as an enable pin. The peak LED current can be further controlled by analog dimming using ADIM1 and ADIM2.

Internal PWM generation uses a resistor to ground on FSET to set the PWM frequency and a voltage on VDR to set the duty cycle, typically a resistor divider from VBIAS to ground. When using internal PWM, the PWM signal is replicated on the PWMOUT pin for cascading multiple A80804s together.

For external PWM mode, connect FSET to VBIAS and apply a PWM signal to each PWMINx pin. The PWMOUT pin stays low while using external PWM.

Extensive protections such as input undervoltage, MOSFET drain short-to-GND, drain short-to-VIN, LED open, and thermal shutdown are incorporated to protect the device and the LEDs. The A80804 also includes LED current derating for high input voltages, based on a programmable threshold, and high internal device temperature.

LED Current Sense Resistor

LED peak current (100%) level can be set independently for each channel by selecting a proper resistor value from each Sx pin to GND as shown in Equation 1:

Equation 1:

$$I_{LEDpeak} = V_{SENSE} / R_{SENSE}$$

where V_{SENSE} is 500 mV for A80804 devices and 200 mV for A80804-1 devices, $I_{LEDpeak}$ is in amps (A), and R_{SENSE} is in Ω .

LED PWM Dimming

A80804 can operate in external PWM mode where each channel can be individually controlled or in internal PWM dimming mode with automatic phase shifting. Tie the FSET pin to VBIAS to use external PWM mode or tie to GND through a resistor for internal PWM mode.

External PWM Dimming

When FSET is tied to VBIAS, the A80804 operates in external PWM mode. A logic-level input signal can be used to control each PWMINx pin to set each respective channel's PWM frequency and duty cycle, allowing each channel to be dimmed

independently.

The external PWM frequency should be between 200 Hz and 1000 Hz with a duty cycle between 5% and 100%. While in external PWM mode, the PWMOUT pin stays low.

The LEDs turn on when each respective PWMINx signal is high. The LED current slew rate is controlled through the SLEW pin and the same slew control is applied to all channels.

For wider dimming ratios, external PWM dimming can be combined with analog dimming.

Internal PWM Dimming

To use the A80804 with internal PWM dimming and automatic phase shifting between each channel, tie the FSET pin to GND through a resistor to set the PWM frequency. The internal PWM frequency range is 100 to 1000 Hz. Use Equation 2 to calculate the resistor value for a PWM frequency.

Equation 2:

$$R_{FPWM} = 5400 / (f_{PWM} - 25)$$

where f_{PWM} is in Hz and R_{FPWM} is in k Ω .

For example, for $f_{PWM} = 200$ Hz, use a 30.9 k Ω resistor.

The internal PWM dimming duty cycle is set with a voltage on the VDR pin. The PWM duty cycle depends on the ratio of the voltage at the VDR and VBIAS pins. For better accuracy, use a voltage divider from VBIAS to VDR. The internal duty cycle range is 2% to 90%. See Equation 3 and Figure 2.

Equation 3:

$$DUTY = 146 \times V_{DR} / V_{BIAS}$$

where V_{DR} and V_{BIAS} are in volts and DUTY is the duty cycle in percent.

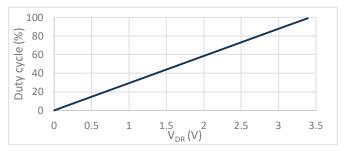


Figure 2: Relationship of External Voltage Input on VDR Pin and Dimming Duty Cycle. V_{DR} can be varied from 0 to 3.6 V.



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Internal PWM Phase Shift

While operating in internal PWM mode, the signal sent to the first channel is delayed 100 μs (typical) from the internal reference PWM signal, and each subsequent channel is delayed another 100 μs (typical) from the previous channel to minimize di/dt and improve EMI. If any channel is not used, the delay for the remaining channels remains the same. For example, if channel 1 and 2 are not used, channel 3 and 4 is still delayed by 300 μs and 400 μs with respect to the internal PWM signal.

Equation 4:

$$t_{CHDELAY} = 100 \ \mu s \times N$$

where N is the channel number.

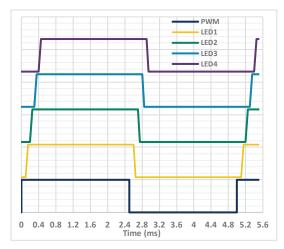


Figure 3: Polyphase Operation with Internal PWM

The polyphase behavior is disabled in external PWM mode since each channel can be independently controlled, and each channel's PWMINx signal can be time-shifted to achieve polyphase operation.

Full Mode

When the FULL pin is pulled high, the A80804 ignores the PWM configuration and operates at 100% duty cycle. The FULL pin does not affect the analog dimming level.

Analog Dimming

Analog dimming is available through ADIM1 and ADIM2. Each ADIMx pin can be tied to VBIAS to disable the dimming for that ADIM pin. When not tied to VBIAS, the voltage on ADIMx scales $V_{\rm SENSE}$, the internal reference voltage that is maintained across $R_{\rm SENSE}$. The lower of the two ADIMx options determines the dimming level. Analog dimming is ratiometric to $V_{\rm BIAS}$. $V_{\rm ADIM1}$ is

the voltage at ADIM1, and V_{ADIM2} is the voltage at ADIM2. The V_{SENSE} reference voltage is also affected by Input Overvoltage Derating and Thermal Derating and Protection Shutdown, and the V_{SENSE} level for regulation is the minimum of all of these circuits.

Analog Dimming with ADIM1

An analog voltage on ADIM1 can be used to derate the peak LED current for binning or other application requirements. While ADIM2 is at V_{BIAS} , to disable dimming on ADIM2, the reference voltage V_{SENSE} scales with ADIM1 based on Equation 5. Use Equation 6 to find the voltage at ADIM1 for a targeted dimming level.

Equation 5:

$$\begin{split} V_{SENSE} &= 0.6371 \times (V_{ADIM1}/V_{BIAS}) - 0.0097 \text{ (A80804)} \\ V_{SENSE} &= 0.2571 \times (V_{ADIM1}/V_{BIAS}) - 0.0057 \text{ (A80804-1)} \end{split}$$

where
$$V_{ADIM2} = V_{BIAS}$$
.

Equation 6:

$$V_{ADIM1} = \left(V_{BIAS} \times (500 \; mV \times DimPct + 0.0097)\right) / \left(0.637 \; (\text{A}80804)\right)$$

$$V_{ADIM1} = \left(V_{BIAS} \times (200 \; mV \times DimPct + 0.0057)\right) / \ 0.2571 \; (\text{A}80804-1)$$

where $V_{ADIM2} = V_{BIAS}$ and DimPct is the dimming percentage target, scaled from 0 to 1.

To use analog dimming with ADIM1, set V_{ADIM1} between 10% and 80% of V_{BIAS} ; see Figure 4.

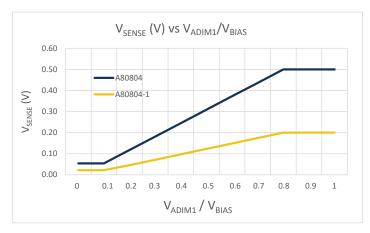


Figure 4: Effect of ADIM1 on V_{SENSE}

Analog Dimming with ADIM2

An analog voltage on ADIM2 can be used to derate the peak LED current, for example with an NTC thermistor to derate the current at high LED temperatures. To use analog dimming with ADIM2, set $V_{\rm ADIM2}$ between 10% to 50% of $V_{\rm BIAS}$; there is no derating



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when V_{ADIM2} is higher than V_{BIAS} / 2. See Equation 7 to calculate V_{SENSE} and Equation 8 to calculate the ADIM2 pin voltage for a targeted dimming ratio.

Equation 7:

$$\begin{split} V_{SENSE} &= 1.125 \times (V_{ADIM2}/V_{BIAS}) - 0.0625 \text{ (A80804)} \\ V_{SENSE} &= 0.450 \times (V_{ADIM2}/V_{BIAS}) - 0.025 \text{ (A80804-1)} \end{split}$$

where $V_{ADIM1} = V_{BIAS}$, and $V_{ADIM2} / V_{BIAS} < 0.5$.

Equation 8:

$$\begin{split} V_{ADIM2} &= \left(V_{BIAS} \times (500 \ mV \times DimPct + 0.0625)\right) / 1.125 \ (\text{A}80804) \\ V_{ADIM2} &= \left(V_{BIAS} \times (200 \ mV \times DimPct + 0.025)\right) / 0.450 \ (\text{A}80804-1) \end{split}$$

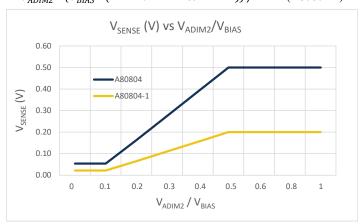


Figure 5: Effect of ADIM2 on V_{SENSE}

When both ADIM1 and ADIM2 are used, V_{SENSE} is the minimum of ADIM1 and ADIM2.

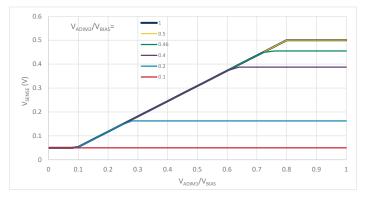


Figure 6: Combined Effect of ADIM1 and ADIM2 pin voltages on V_{SENSE} for A80804

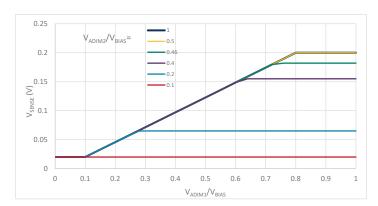


Figure 7: Combined Effect of ADIM1 and ADIM2 pin voltages on V_{SENSE} for A80804-1

LED Current Slew Control

The LED current rise and fall times can be controlled with the SLEW pin. This allows the system designer to optimize for PWM duty cycle accuracy or EMI performance. When SLEW is tied to logic high, the 10% to 90% slew time is 80 μ s, the slowest slew rate option. When SLEW is connected to logic low, the slew time is 6 μ s, the fastest slew rate option. For a slew rate between the low and high levels, connect SLEW to GND through a resistor using Equation 9.

Equation 9:

$$t_{SLEW} = R_{SLEW} / 4$$

where t_{SLEW} is in μs and R_{SLEW} is in $k\Omega$. Use a value of R_{SLEW} between 324 $k\Omega$ (80 μs) and 24.3 $k\Omega$ (6 μs).

PWMOUT

The A80804 has a PWMOUT pin that replicates the reference PWM signal used while in internal PWM mode. This signal can be used as the PWMINx signal for peripheral devices to synchronize the peripheral device with the controller device. Since the PWMINx pins are driven from PWMOUT, the peripheral device must operate in external PWM mode. Therefore, the peripheral device does not have the PWM channel phase shifting but uses the controller's internal PWM reference which is 100 µs ahead of the channel 1 on the controller; see the Multiple A80804 Controller-Peripheral Arrangement application.

PWMOUT is low while in external PWM mode.



MINOUT

The MINOUT pin provides an output voltage proportional to the minimum voltage of the Dx pins for all active channels. The voltage from MINOUT can be fed to a voltage regulator's feedback pin to complete a closed-loop system and trim the regulated output leading to the LEDs. The voltage on MINOUT is given by Equation 10 with minimum of 0.3 V (typical) and maximum of 3.5 V (typical).

Equation 10:

 $V_{MINOIIT} = 10 \times (V_{Dx\ MIN} - 0.8) + 0.3$

Figure 8: Block Diagram of MINOUT Block

An example of a pre-regulator powering the LED strings is shown in Figure 9. The MINOUT signal feeds into the regulator control loop through an external resistor, RFB3.

Equation 11 can be used to calculate the resistor values.

Equation 11:

$$R_{FB3} = \left[\frac{V_{MINOUT(\max)} \times (V_{OUT(\max)} - V_{FB})}{V_{FB} \times (V_{OUT(\max)} - V_{OUT(\min)})} - 1 \right] \times R_{FB2}$$

$$R_{FB1} = \left[\frac{V_{OUT(\max)} - V_{FB}}{V_{FB}} \right] \times \left[\frac{R_{FB2} \times R_{FB3}}{R_{FB2} + R_{FB3}} \right]$$

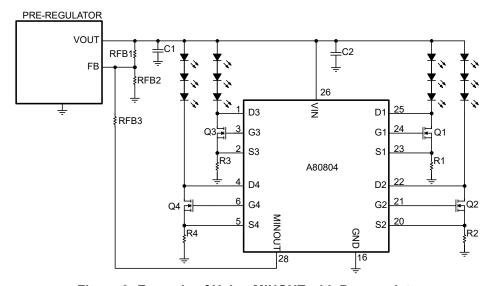
 $V_{OUT(min)}$ and $V_{OUT(max)}$ are the worst-case required voltages for the LEDs to operate, and V_{FB} is the feedback voltage of the pre-regulator.

Protection Functions

The A80804 asserts a fault by pulling the nFAULT pin low when a fault is detected for three consecutive PWM cycles. The 3-cycle count prevents fault assertion on a spurious transient. The device returns to normal operation immediately after the fault is removed. Any faulted LED string operates at 5% duty cycle during the PWM on-time to minimize power dissipation in the MOS-FETs and detect fault recovery. While in FULL mode, the device waits 6 ms to assert the nFAULT pin low. While in external PWM mode or FULL mode, the faulted LED string is driven with a 500 Hz, 5% duty cycle PWM signal to detect fault recovery.

MODE Pin Behavior

When a fault occurs on one LED string, the behavior of other strings is determined by the state of the MODE pin. Other strings continue to operate normally when MODE is low ("one-out-continue" or



SX

Figure 9: Example of Using MINOUT with Pre-regulator



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"N-1" mode) and shutdown when MODE is high ("one-out-all-out" mode). The nFAULT pin becomes bidirectional and acts as both a fault input and output when MODE is high, which can be used to pass the fault state to peripheral or paralleled devices.

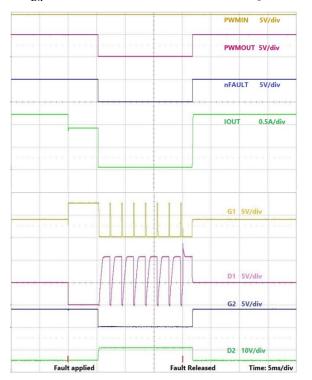
FDIS Pin for Fault Disable

Open LED and MOSFET drain short-to-GND faults are disabled when the input voltage is less than five times the voltage at the FDIS pin, $V_{IN} < 5 \times V_{FDIS}$. Select a V_{FDIS} level higher than the LED string's forward voltage to prevent faults during startup or V_{IN} transients.

OPEN LED

An open LED fault is detected when V_{IN} > 5 × V_{FDIS} and V_{Dx} < 0.24 V.

Once the fault is detected, nFAULT is asserted low and that LED channel operates with 5% duty cycle even if FULL is high, keeping the MOSFET on with a low duty cycle to detect removal of the fault for auto-recovery. The LED current in the faulted string is zero since the LED current path is open. When the fault is removed, $V_{\rm Dx} > 0.24$ V, the device returns to normal operation.



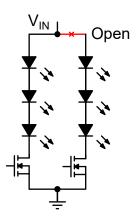


Figure 10: LED Open Protection

If MODE is high, all other gates, Gx, and PWMOUT are pulled low once the fault is detected; parallel or peripheral devices also turn off when nFAULT goes low if MODE is high, or when PWMOUT is pulled low if cascading PWMOUT to PWMINx of another device. If MODE is low all other gates, Gx, and PWMOUT are unaffected and continue to operate normally.

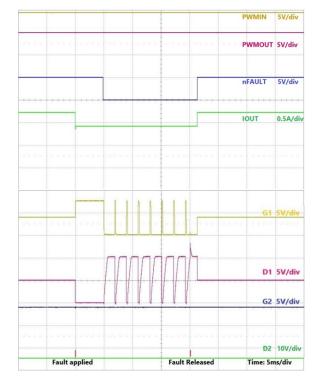


Figure 11: Open LED Fault on D1 in FULL mode. MODE = High (left), MODE = Low (right). Fault on channel 1.



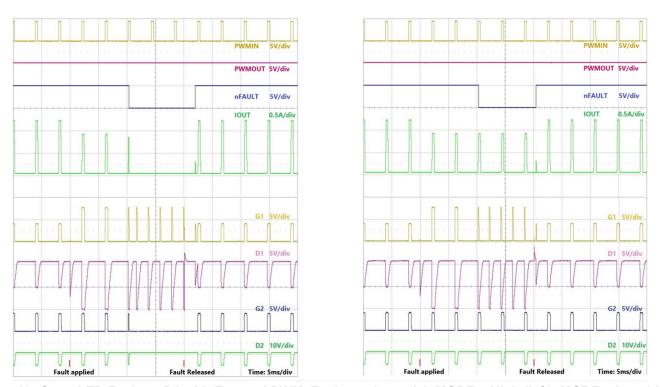


Figure 12: Open LED Fault on D1 with External PWM. Fault on channel 1. MODE = High (left), MODE = Low (right).

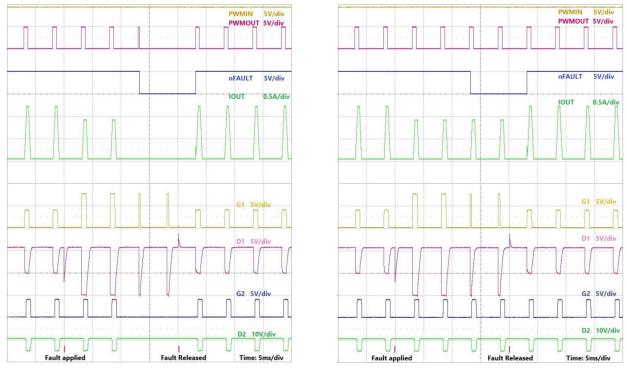


Figure 13: Open LED Fault on D1 with Internal PWM. Fault on channel 1. MODE = High (left), MODE = Low (right).



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Short Circuit Protection

The A80804 can protect against multiple short-circuit faults scenarios, as shown in Figure 14.

Drain Short To GND

A MOSFET drain short-to-ground fault is detected when $V_{\rm IN} > 5 \times V_{\rm FDIS}$ and $V_{\rm Dx} < 0.24$ V. Once the fault is detected, nFAULT is asserted low and that LED channel operates with 5% duty cycle, even if FULL is high, to detect fault removal for autorecovery. The drain short-to-ground fault is not a latched fault. When the fault is removed, $V_{\rm Dx} > 0.24$ V, the device returns to normal operation. If MODE is high, all other gates, Gx, and PWMOUT are pulled low when the fault is detected; parallel or peripheral devices also turn off when nFAULT goes low if the nFAULT pins are tied together and MODE is high. If MODE is low, the other gates and PWMOUT are unaffected and continue to operate normally. During a drain short-to-ground fault, the LED string may see a large current as the LED string is shorted to ground.

The operating waveforms Gx, Dx, PWMOUT, and nFAULT, are the same for drain short-to-GND fault and open LED fault except the faulty LED string sees large current when the drain is shorted to ground.

Drain Short To VIN

A MOSFET drain short-to-VIN, a full LED string short, is detected when $(V_{IN} - V_{Dx}) < 0.8$ V and the configured LED current slew time has elapsed while PWMINx is high. Once the fault is detected, nFAULT is asserted low and that LED channel operates with 5% duty cycle even if FULL is high, keeping the MOSFET on with a low duty cycle to detect removal of the fault for auto-recovery and minimize power dissipation in the faulty LED string. The drain short-to-VIN fault is not a latched fault. When the fault is removed, $(V_{IN} - V_{Dx}) > 0.8$ V, the device returns to normal operation. The current in the faulted LED string during the fault is zero since the LED string is shorted out when the MOSFET drain is shorted to VIN.

If MODE is high, all other gates, Gx, and PWMOUT are pulled low once the fault is detected; parallel or peripheral devices also turn off when nFAULT goes low if the nFAULT pins are tied together and MODE is high. If MODE is low, all other gates, Gx, and PWMOUT are unaffected and continue to operate normally.

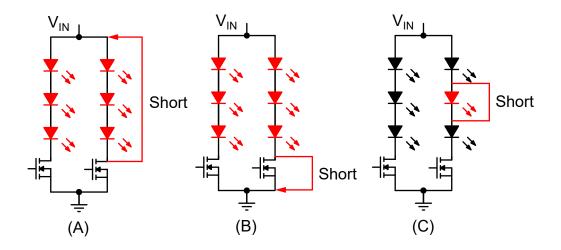


Figure 14: Short-Circuit Protection



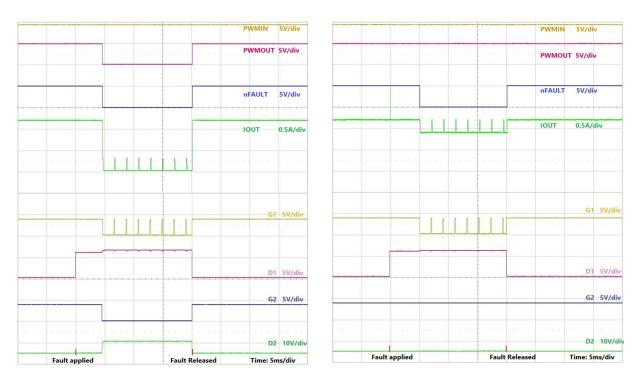


Figure 15: Drain Short to VIN Fault on D1 in FULL mode. MODE = High (left), MODE = Low (right).

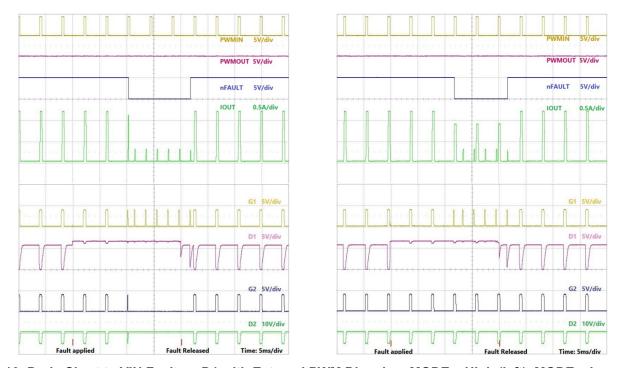
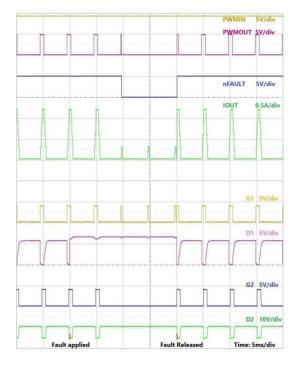


Figure 16: Drain Short to VIN Fault on D1 with External PWM Dimming. MODE = High (left), MODE = Low (right).





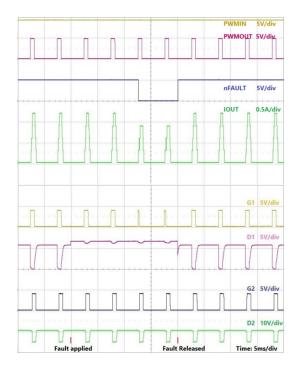


Figure 17: Drain Short to VIN Fault on D1 with Internal PWM Dimming. MODE = High (left), MODE = Low (right).

LED Short Response

If less than the full LED string is shorted, the A80804 continues to work normally. This leads to increased power dissipation in the LED string's MOSFET.

Input Undervoltage Protection

When input voltage, V_{IN} , is below the undervoltage lockout threshold defined by five times the voltage on the UVLO pin, V_{IN} < $5 \times V_{UVLO}$, an input undervoltage fault is detected. If MODE is high while an undervoltage fault occurs, the device is off, and if MODE is low, the device stays on. The fault flag nFAULT is not affected by this fault.

Input Overvoltage Derating

The A80804 can derate the LED current at higher input voltages to limit the power dissipation in the MOSFETs. The input voltage level to start derating, $V_{INth(L)}$, is ten times the voltage at the VINDERAT pin plus 0.7 V, $10 \times V_{VINDERAT} + 0.7$ V, and is typically set with a resistor divider from VBIAS pin to VINDERAT pin. The level for maximum derating, $V_{INth(H)}$ is higher than $V_{INth(L)}$ by V_{INthd} (typically 2.16 V). The reference voltage, V_{SENSE} , decreases to 90% of its nominal value at $V_{INth(L)}$ and to 60% at $V_{INth(H)}$; see Figure 18 and Figure 19. The maximum derating is 50% for higher input voltage levels. See Equation 12 to calculate the voltage at

VINDERAT pin for a target V_{INth(L)} level.

Equation 12:

$$V_{VINDERAT} = (V_{INth(L)} - 0.7) / 10$$

For example, when $V_{VINDERAT}$ = 2.0 V, V_{SENSE} derates to 90% of its nominal value when V_{IN} = 20.7 V.

Even if the VINDERAT pin is tied to VBIAS, the A80804 begins derating the LED current at 35 V (typical).

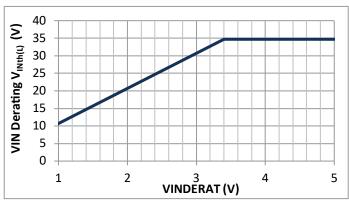


Figure 18: V_{INDERAT} Voltage versus V_{IN} Derating Threshold

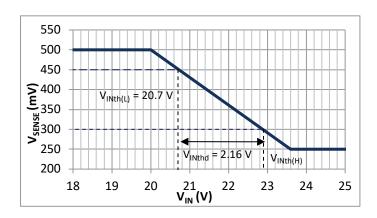


Figure 19: Output Current Foldback Based on $V_{\rm IN}$

Thermal Derating and Protection Shutdown

At higher temperatures, the A80804 derates the LED current to limit power dissipation in the external MOSFETs. The reference voltage, $V_{\rm SENSE}$, decreases with increasing $T_{\rm J}$ as shown in Figure 20, where $V_{\rm SENSE}$ derates to 90% at 149°C (typical) and 35% at 163°C (typical). The maximum thermal derating is 25% of the nominal current. Thermal shutdown ($T_{\rm SD}$) completely disables the outputs under extreme overtemperature conditions (>170°C), and nFAULT goes low. The A80804 restarts when the temperature drops by 30°C.

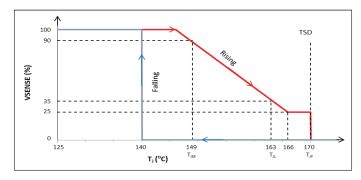


Figure 20: Output Current Foldback Based on Rising T_J

The combined effect of $V_{\mbox{\footnotesize{IN}}}$ and thermal derating is shown in Figure 21.

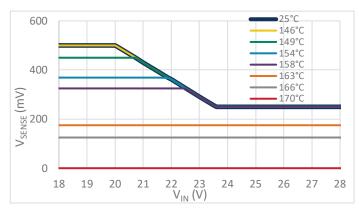


Figure 21: Combined Effect of V_{IN} Derating and Thermal Derating

LED peak current also depends on voltage on ADIMx pin even during $V_{\rm IN}$ and thermal derating.

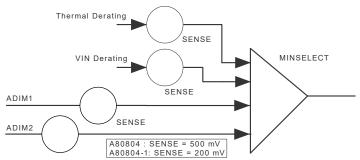


Figure 22: Analog Dimming and Derating Block Diagram

Shutdown

While operating in internal PWM mode, each LED channel resets when its corresponding PWMINx pin is pulled low. While operating in external PWM mode, each LED channel resets when its corresponding PWMINx pin is pulled low for more than 20 ms.

When a channel is reset, its corresponding gate is pulled low and any faults associated with that channel are reset. The rest of the device operates normally. If a faulty string is disabled by pulling PWMINx pin low for greater than 20 ms, the device returns to normal operation for remaining channels and nFAULT is released.



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Table 1: Fault Operation and Derating (Internal PWM mode)

	nEALILT		MODE = VBIAS	MODE = Low			
	nFAULT	PWMOUT	Operation	PWMOUT	Operation		
Drain Shorted to VIN	Low	Low	Detected for three consecutive PWM cycles when $(V_{\text{IN}} - V_{\text{Dx}}) < 0.8 \text{ V}$. The faulty MOSFET remains on with 5% PWM. Other strings, PWMOUT, and nFAULT pulled low once fault detected. The fault is not latched. The faulty MOSFET drops the full input voltage during PWM on-time. The device recovers to normal operation when the fault is removed.	Normal	Detected for three consecutive PWM cycles when $(V_{IN}-V_{Dx})$ < 0.8 V. The faulty MOSFET remains on with 5% PWM, rest of IC operates normally except nFAULT pin is pulled low. The faulty MOSFET drop full input voltage during PWM on-time. The device recovers to normal operation when the fault is removed.		
	The fault is	detected wh	en corresponding PWMIN pin is high and the con	figured slew t	ime has elapsed.		
Open LED	Low	Low	Detected for three consecutive PWM cycles when $V_{\rm IN}$ > 5 × $V_{\rm FDIS}$ and $V_{\rm DX}$ < 0.24 V. The faulty MOSFET remains on with 5% PWM. Other strings, PWMOUT, and nFAULT pulled low once fault detected. The fault is not latched. The device recovers to normal operation when fault removed.	Normal	Detected for three consecutive PWM cycles when $V_{\text{IN}} > V_{\text{FDIS}}$ and $V_{\text{Dx}} < 0.24$ V. The faulty MOSFET remains on with 5% PWM, rest of the device operates normally except nFAULT pin is pulled low. nFAULT pin goes high when the fault is removed.		
Drain Shorted to GND	Low	Low	Detected for three consecutive PWM cycles when $V_{\rm IN} > 5 \times V_{\rm FDIS}$ and $V_{\rm Dx} < 0.24$ V. The faulty string remains on with 5% PWM. Other strings, PWMOUT, and nFAULT pulled low once fault detected. The fault is not latched. The device recovers to normal operation when fault removed. LEDs in faulty string may be damaged due to excessive LED current.	Normal	Detected for three consecutive PWM cycles when $V_{\text{IN}} > V_{\text{FDIS}}$ and $V_{\text{Dx}} < 0.24$ V. The faulty string remains on with 5% PWM, rest of the device operates normally except nFAULT pin is pulled low LEDs in faulty string may damage due to excessive LED current. The nFAULT pin goes high when the fault is removed.		
Source Shorted to GND	Low	Low	All LED channels are turned off until the fault is removed and the A80804 is power-cycled.	Low	All LED channels are turned off until the fault is removed and the A80804 is power-cycled.		
Thermal Derating	Normal	Normal	LED current derates based on junction temperature.	Same opera	tion as MODE = VBIAS		
VIN Derating	Normal	Normal	LED current derates based on supply voltage and VINDERAT setting.	Same operation as MODE = VBIAS			
TSD	Low	Low	LEDs turn off when T _J exceeds 170°C and auto-recovers when T _J drops below 140°C.	Normal LEDs turn off when T _J exceeds 170°0 PWMOUT is normal. The device autorecovers when T _J drops below 140°C			
VIN Undervoltage	Normal	Low	LEDs turn off when $V_{IN} < V_{INUV} - V_{INUVhys}$ and auto-restart when V_{IN} rises above V_{INUV} .	Normal	A80804 operates normally. LED current may reduce if $V_{\rm IN}$ < $V_{\rm F}$. nFAULT is not affected.		



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Table 2: Fault Operation and Derating (External PWM mode)

	nFAULT		MODE = VBIAS	MODE = Low			
	IIFAULI	PWMOUT	/MOUT Operation		Operation		
Drain Shorted Low to VIN		Low	Detected for three consecutive PWM cycles when $(V_{\text{IN}} - V_{\text{Dx}})$ < 0.8 V. The faulty string remains on with 5%, 500 Hz PWM. Other strings, PWMOUT, and nFAULT pulled low once fault detected. Faulty MOSFET drops full VIN voltage during PWM. IC recovers to normal operation when fault removed.	Low	Detected for three consecutive PWM cycles when $(V_{\rm IN}-V_{\rm Dx})$ < 0.8 V. The faulty string remains on with 5%, 500 Hz PWM. Rest of the IC operates normally except nFAULT pin pulled low. Faulty MOSFET drops full VIN voltage during PWM IC recovers to normal operation when fault removed.		
	The fault is	detected wh	en all PWMIN high and after completion of refere	nce ramp.			
Open LED	Low	Low	Detected for three consecutive PWM cycles when $V_{\rm IN}$ > 5 × $V_{\rm FDIS}$ and $V_{\rm DX}$ < 0.24 V. The faulty string remains on with 5%, 500 Hz PWM. Other strings, PWMOUT, and nFAULT pulled low once fault detected. IC recovers to normal operation when fault removed.	Low	Detected for three consecutive PWM cycles when $V_{\text{IN}} > V_{\text{FDIS}}$ and $V_{\text{Dx}} < 0.24$ V. The faulty string remains on with 5%, 500 Hz PWM, rest of IC operates normally except nFAULT pin pulled low. nFAULT pin goes high when fault removed.		
Drain Shorted to GND	Low	Low	Detected for three consecutive PWM cycles when $V_{IN} > 5 \times V_{FDIS}$ and $V_{DX} < 0.24$ V. The faulty string remains on with 5%, 500 Hz PWM. Other strings, PWMOUT, and nFAULT pulled low once fault detected. IC recovers to normal operation when fault removed. LEDs in faulty string may damage due to excessive LED current.	Low	Detected for three consecutive PWM cycles when $V_{\text{IN}} > V_{\text{FDIS}}$ and $V_{\text{Dx}} < 0.24$ V. The faulty string remains on with 5%, 500 Hz PWM, rest of IC operates normally except nFAULT pin pulled low. nFAULT pin goes high when fault removed. LEDs in faulty string may damage due to excessive LED current.		
Source Shorted to GND	Low	Low	All LED channels are turned off until the fault is removed and the A80804 is power-cycled.	Low All LED channels are turned off until the is removed and the A80804 is power-or			

VIN derating, Thermal derating, TSD, and VIN undervoltage fault operation is same as described in Table 1.



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Table 3: Fault Operation and Derating (FULL mode)

	nFAULT	MODE = VBIAS		MODE = Low			
	PWMOU		Operation	PWMOUT	Operation		
Drain Shorted to VIN	Low	Low	Detected when $(V_{IN} - V_{Dx}) < 0.8 \text{ V}$ for 6 ms. The faulty string remains on with 5%, 500 Hz PWM. Other strings, PWMOUT, and nFAULT pulled low once fault detected but not latched. Faulty MOSFET drop full VIN voltage during PWM. IC recovers to normal operation when fault removed.	Normal	Detected when $(V_{IN}-V_{Dx})$ < 0.8 V for 6 ms. The faulty string remains on with 5%, 500 Hz PWM, rest of IC operates normally except nFAULT pin pulled low. Faulty MOSFET drop full VIN voltage during PWM. IC recovers to normal operation when fault removed.		
	The fault is	detected wh	en all PWMIN high and after completion of refere	nce ramp.			
Open LED	Low	Low	Detected when $V_{\rm IN}$ > 5 × $V_{\rm FDIS}$ and $V_{\rm Dx}$ < 0.24 V for 6 ms. The faulty string remains on with 5%, 500 Hz PWM. Other strings, PWMOUT, and nFAULT pulled low once fault detected but not latched. IC recovers to normal operation when fault removed.	Normal	Detected when $V_{\text{IN}} > V_{\text{FDIS}}$ and $V_{\text{Dx}} < 0.24 \text{ V}$ for 6 ms. The faulty string remains on with 5%, 500 Hz PWM, rest of IC operates normally except nFAULT pin pulled low. nFAULT pin goes high when fault removed.		
Drain Shorted to GND	Low	Low	Detected when $V_{\rm IN}$ > 5 × $V_{\rm FDIS}$ and $V_{\rm Dx}$ < 0.24 V for 6 ms. The faulty string remains on with 500 Hz, 5% PWM. Other strings, PWMOUT, and nFAULT pulled low once fault detected but not latched. IC recovers to normal operation when fault removed LEDs in faulty string may damage due to excessive LED current.	Normal	Detected when $V_{\text{IN}} > V_{\text{FDIS}}$ and $V_{\text{Dx}} < 0.24 \text{ V}$ for 6 ms. The faulty string remains on with 500 Hz, 5% PWM, rest of IC operates normally except nFAULT pin pulled low LEDs in faulty string may damage due to excessive LED current. nFAULT pin goes high when fault removed.		
Source Shorted to GND	Low	Low	All LED channels are turned off until the fault is removed and the A80804 is power-cycled.	Low All LED channels are turned off until is removed and the A80804 is power.			

 $VIN\ derating,\ Thermal\ derating,\ TSD,\ and\ VIN\ undervoltage\ fault\ operation\ is\ same\ as\ described\ in\ Table\ 1.$



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Table 4: Simplified Fault Table

			MODE = HIGH			MODE = LOW				
Description	Detection Condition	FULL	nFAULT	Faulty Gate	NORMAL Gates	PWM_ OUT [3]	nFAULT	Faulty Gate	NORMAL Gates	PWM_ OUT [3]
Drain Shorted	$V_{IN} - V_{Dx} < typ 0.8 V$	HIGH	LOW	5% PWM	LOW	LOW	LOW	5% PWM	HIGH	HIGH
to VIN ^[1] (min 0.5 V, max 1.1 V)	LOW	LOW	5% PWM	LOW	LOW	LOW	5% PWM	PWM	PWM	
Open LED	Open LED V _{Dx} < typ 0.24 V	HIGH	LOW	5% PWM	LOW	LOW	LOW	5% PWM	HIGH	HIGH
Fault [2]	(min 0.19 V, max 0.29 V)	LOW	LOW	5% PWM	LOW	LOW	LOW	5% PWM	PWM	PWM
Drain Shorted	V _{Dx} < typ 0.24 V	HIGH	LOW	5% PWM	LOW	LOW	LOW	5% PWM	HIGH	HIGH
to GND [2]	(min 0.19 V, max 0.29 V)	LOW	LOW	5% PWM	LOW	LOW	LOW	5% PWM	PWM	PWM
Thermal Shutdown	T _J > 170°C	Х	LOW	LOW	LOW	LOW	LOW	LOW	LOW	Normal

X = Don't Care

Table 5: Latching Faults

Description	Mode	Detection Condition	Operation	Reset Mechanism
Current Sense Shorted to GND	one-out-all-out or one-out-continue	$V_{Sx} < (V_{SENSE}/2), V_{Gx} = ON $ and $V_{Dx} > 250 $ mV	All channels are turned off and remain off until VIN is cycled. nFAULT remains low.	Cycle VIN
Supply to LEDs goes away while VIN supply remains	one-out-all-out	Open LED fault triggered on multiple channels. Because of the one-out-all-out operation, the first channel to detect the fault disables the others. Then the next channel to detect the fault disables the first.	All channels remain off until VIN or all PWMINx pins are cycled. nFAULT remains low.	Cycle VIN or all PWMINx pins



^[1] Detected after completion of slew time.

^[2] V_{IN} > 5 × V_{FDIS}. [3] Applicable only for FULL and internal PWM mode.

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APPLICATIONS INFORMATION

MOSFET Selection Guidelines

The A80804 uses N-channel MOSFETs for controlling the LED current. The following should be considered when selecting a MOSFET:

- Drain-source voltage must be higher than the maximum input voltage.
- Drain current rating must be higher than LED current.
- For low voltage operation (V_{IN} < 7 V), select a logic level MOSFET.
- The MOSFETs power dissipation is at the worst-case condition in FULL mode at max V_{IN}, based on Equation 13.
 Equation 13:

$$P_D = (V_{IN(max)} - V_{Fmin}) \times I_{LED}$$

 Select MOSFET to handle the power without exceeding junction temperature rating, T_J, of the MOSFET. A proper PCB layout is recommended to minimize temperature rise.

- MOSFET input capacitance, C_{iss} should be 250 pF < C_{iss} < 2000 pF.
- MOSFETs can be paralleled with above considerations.

Some recommended MOSFETs are given below in Table 6.

Table 6: Sample of Possible MOSFETs

Max. Input Voltage = 40 V							
Part Number	V _{DS} (V)	I _D (A)	Package	C _{iss} (pF)	Application		
BUK7M67-60E	60	14	LFPAK33	250	I _{LED} < 300 mA, V _{IN} > 7 V		
RD3L080S	60	8	DPAK	380	I _{LED} < 700 mA		
NVD5867NL	60	22	DPAK	675	I _{LED} < 700 mA		
BUK7675-55A	55	20.3	D2PAK	320	I _{LED} > 700 mA		

Note: These MOSFETs are only for guidance, actual selection depends on application requirements and required power dissipation (thermal design).



Four 2-LED Channels, Internal PWM at 200 Hz, 5% Duty Cycle, Without Analog Dimming

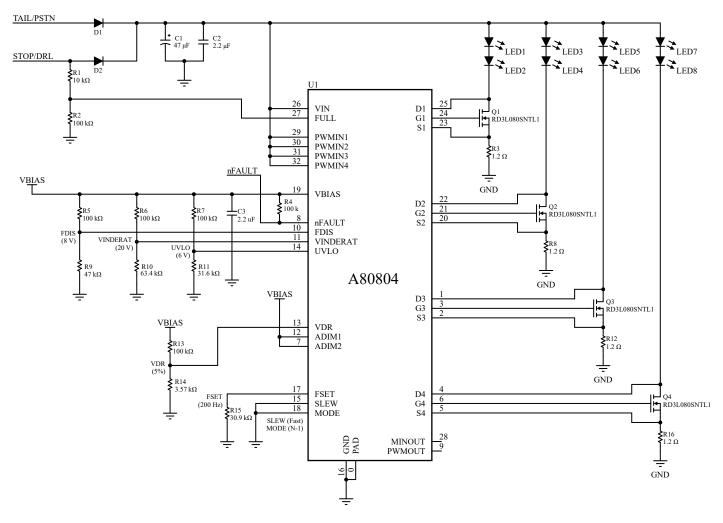


Figure 23: Application Circuit for Four 2-LED Channels, Internal PWM at 200 Hz, 5% Duty Cycle, Without Analog Dimming

Design Requirements

Requirement	Value	Unit
V _{IN(MIN)} (UVLO)	6	V
V _{IN(MIN)} (regulation)	8	V
$V_{F(max)}$	6.4	V
I _{LED}	400	mA
f _{PWM}	200	Hz
Duty Cycle (D)	5	%
V _{IN} Derate Start	20	V
No analog dimming	_	_



High-Current Four-Channel Automotive LED Controller

Bill of Materials

Designator	Description	Quantity
C1	Capacitor, Electrolytic, 47 µF, 50 V, 10%	1
C2	Capacitor, Ceramic, 2.2 µF, 50 V, 10%, X7R	1
C3	Capacitor, Ceramic, 2.2 µF, 16 V, 10%, X7R	1
D1, D2	Diode	2
LED1, LED2, LED3, LED4, LED5, LED6, LED7, LED8	LED 3 V	8
Q1, Q2, Q3, Q4	MOSFET N-CH 60 V 8 A TO-252-2 (DPAK)	4
R1, R2, R4, R5, R6, R7, R13	Resistor, 100 kΩ, 1/8 W, 1 %, 0603	7
R3, R8, R12, R16	Resistor, 1.2 Ω, 1/2 W, 1 %, 1206	4
R9	Resistor, 47 kΩ, 1/8 W, 1 %, 0603	1
R10	Resistor, 63.4 kΩ, 1/8 W, 1 %, 0603	1
R11	Resistor, 31.6 kΩ, 1/8 W, 1 %, 0603	1
R14	Resistor, 3.57 kΩ, 1/8 W, 1 %, 0603	1
R15	Resistor, 30.9 kΩ, 1/8 W, 1 %,0603	1
U1	A80804 in QFN-32	1



Four 2-LED Channels, External PWM, Analog Dimming at 80%

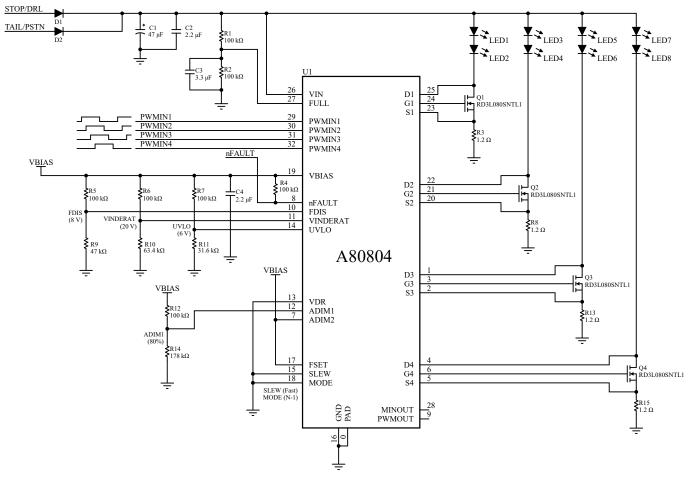


Figure 24: Application Circuit for Four 2-LED Channels, External PWM, Analog Dimming at 80%

Design Requirements

Requirement	Value	Unit
V _{IN(MIN)} (UVLO)	6	V
V _{IN(MIN)} (regulation)	8	V
$V_{F(max)}$	6.4	V
I _{LED}	400	mA
f _{PWM}	External	Hz
Duty Cycle (D)	External	%
V _{IN} Derate Start	20	V
ADIM1	80	%



High-Current Four-Channel Automotive LED Controller

Bill of Materials

Designator	Description	Quantity
C1	Capacitor, Electrolytic, 47 µF, 50 V, 10%	1
C2	Capacitor, Ceramic, 2.2 µF, 50 V, 10%, X7R	1
C3	Capacitor, Ceramic, 3.3 µF, 50 V, 10%, X7R	1
C4	Capacitor, Ceramic, 2.2 µF, 16 V, 10%, X7R	1
D1, D2	Diode	2
LED1, LED2, LED3, LED4, LED5, LED6, LED7, LED8	LED 3 V	8
Q1, Q2, Q3, Q4	MOSFET N-CH 60 V 8 A TO-252-2 (DPAK)	4
R1, R2, R4, R5, R6, R7, R12	Resistor, 100 kΩ, 1/8 W, 1 %, 0603	7
R3, R8, R13, R15	Resistor, 1.2 Ω, 1/2 W, 1 %, 1206	4
R9	Resistor, 47 kΩ, 1/8 W, 1 %, 0603	1
R10	Resistor, 63.4 kΩ, 1/8 W, 1 %, 0603	1
R11	Resistor, 31.6 kΩ, 1/8 W, 1 %, 0603	1
R14	Resistor, 178 kΩ, 1/8 W, 1 %, 0603	1
U1	A80804 in QFN-32	1



Multiple A80804 Controller-Peripheral Arrangement

The controller IC is configured as a single IC in Internal PWM mode. In TAIL mode, a resistor on the FSET pin determines the PWM frequency, and the duty cycle is controlled by voltage on the VDR pin. In Full mode, duty cycle is always 100%.

Operating PWM frequency and duty cycle output is provided on the PWMOUT pin. Connect this pin to the PWMINx pins of the peripheral ICs. Each peripheral IC is configured in external PWM mode.

Controllers and peripherals derate LED current independently, based on VIN pin voltage and junction temperature of the respective device. Overtemperature or input overvoltage conditions derate LED current by controlling peak current in both Stop and Tail modes.

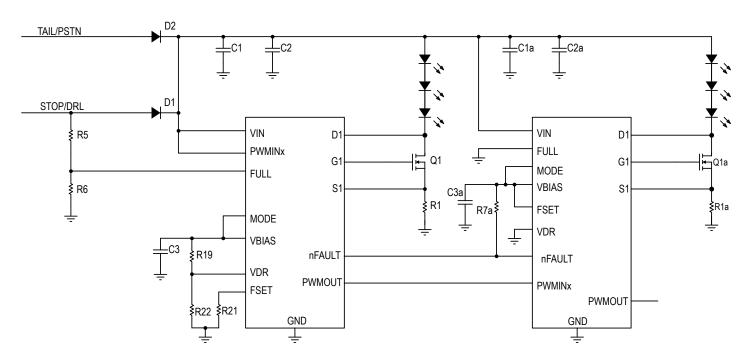


Figure 25: Controller-Peripheral Operation with Internal PWM. Only one channel shown for simplicity.



Multiple A80804 In Parallel with External Dimming

All the A80084 devices are configured for external PWM mode. PWM input from the MCU controls frequency and duty cycle in Tail mode. In Stop mode, duty cycle is always 100%.

Each IC derates LED current independently, based on VIN pin voltage and junction temperature of the respective IC.

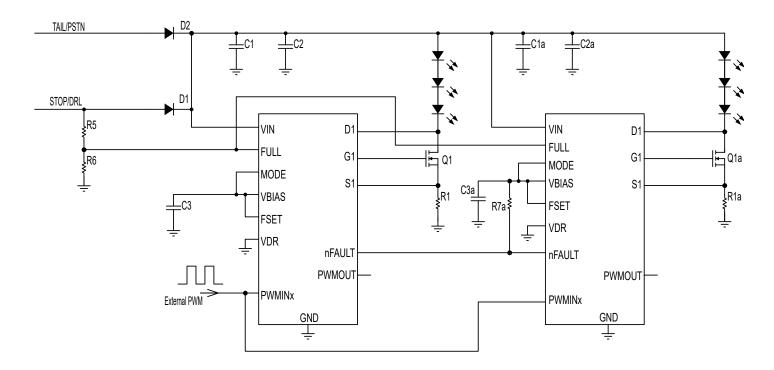


Figure 26: Parallel Operation with External PWM. Only one channel shown for simplicity.



Sequential LED Driver

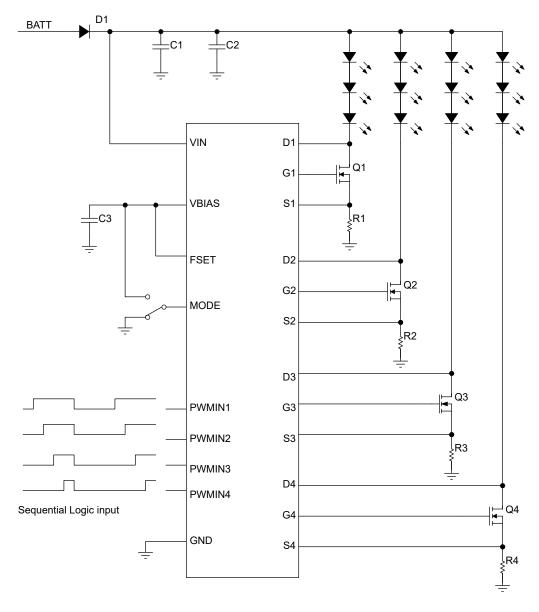


Figure 27: Sequential LED driver
Each sequence is approximately 50-200 ms and off period could be up to 0.6 seconds. Faults reset in each cycle as off period is > 20 ms.



LED Binning and NTC Derating

This application example demonstrates LED binning and thermal derating using ADIM1 and ADIM2. The schematic shows a simplified A80804 to focus on the analog dimming pins, which are controlled by a voltage divider from V_{BIAS} . The bottom of the voltage divider is mounted on the remote LED board allowing each LED board to adjust its own analog dimming behavior. ADIM1 is used for LED binning and ADIM2 is used for LED temperature derating, configured to begin derating the LED current when the temperature exceeds 100° C. Figure 28 below shows two possible remote LED boards with a different binning configuration and the same temperature derating configuration.

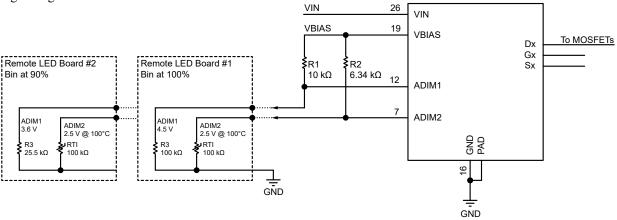


Figure 28: A80804 Analog Dimming with Remote LEDs

Use Equation 6 to calculate the voltage at the ADIM1 pin for the LED binning requirements. Set the top resistor of the voltage divider to $10 \text{ k}\Omega$ and use Equation 14 to solve for the bottom resistor, where V_{ADIM1} is 3.6 V for 90% dimming and at least 4.0 V for 100% dimming. Equation 14:

$$R_{BOT} = \frac{V_{ADIM1} \times R_{TOP}}{V_{BIAS} - V_{ADIM1}}$$

For temperature derating with ADIM2, select an NTC thermistor, in this case a Vishay NTCS0603E3104FXT 100 k Ω thermistor, and use Equation 15 to calculate the NTC resistance value at 100°C. Use Equation 16 to calculate the resistance of the top of the voltage divider for ADIM2.

Equation 15:

$$R_{NTC(100C)} = 100 \text{ k}\Omega \times e^{\beta} \left(\frac{1}{(100 + 273.15)} - \frac{1}{(25 + 273.15)} \right) = 6.34 \text{ k}\Omega$$

Equation 16:

$$R_{ADIM2(TOP)} = R_{NTC(100C)} \left(\frac{V_{BIAS}}{V_{ADIM2}} - 1 \right) = 6.34 \text{ k}\Omega \left(\frac{5}{2.5} - 1 \right) = 6.34 \text{ k}\Omega$$

The LED current is controlled by the minimum of ADIM1 and ADIM2. If ADIM1 is used to scale the LED current, ADIM2 does not affect



the LED current until lower than ADIM1, as seen in the red curves in Figure 29.

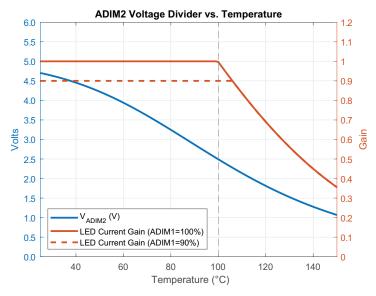


Figure 29: V_{ADIM2} vs. Temperature

Table 7: Component Values

Component	LED Board 1	LED Board 2
ADIM1 RTOP	10 kΩ	10 kΩ
ADIM1 RBOT	100 kΩ	25.5 kΩ
ADIM2 RTOP	6.34 kΩ	6.34 kΩ
ADIM2 NTC R0	100 kΩ	100 kΩ

Table 8: Design Results

		LED Board 1				LED Board 2		
Temperature (°C)	V _{ADIM1} (V)	V _{ADIM2} (V)	V _{SENSE} (V)	LED Current Gain	V _{ADIM1} (V)	V _{ADIM2} (V)	V _{SENSE} (V)	LED Current Gain
25	4.55	4.70	0.50	1.00	3.60	4.70	0.45	0.90
90	4.55	2.87	0.50	1.00	3.60	2.87	0.45	0.90
100	4.55	2.49	0.49	0.99	3.60	2.49	0.45	0.90
110	4.55	2.14	0.42	0.84	3.60	2.14	0.42	0.84
120	4.55	1.81	0.35	0.69	3.60	1.81	0.35	0.69
130	4.55	1.53	0.28	0.56	3.60	1.53	0.28	0.56

Parallel MOSFET Arrangement for High-Power Application

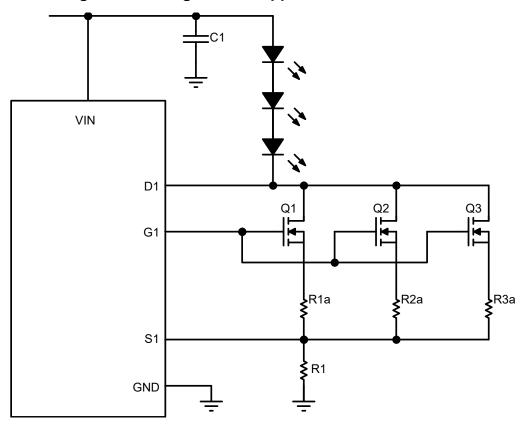


Figure 30: Parallel MOSFET Arrangement for High Power Application

R1a, R2a, and R3a helps in balancing current through MOSFET. Typically for 0.3 A select 1 Ω resistor. Total input capacitance of MOSFETs should be as specified by C_{iss} requirement in MOSFET Selection Guidelines.

Arrangement to Avoid LED Current in External PWM Mode with Full Pin Connected to VIN and PWMINx Held Low at Startup

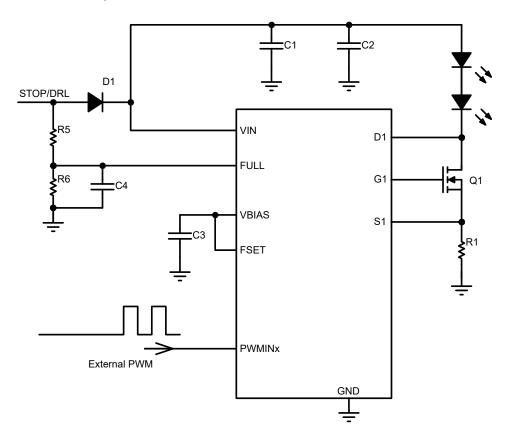


Figure 31: Application to avoid initial LED current in external PWM mode with FULL pin connected to VIN and PWMINx held low at startup.

Design R5-R6 and C4 network to limit voltage on the FULL pin to below 1 V within 20 ms from startup.

If the FULL pin is driven externally such as through a microcontroller, provide a 20 ms delay from startup on the FULL pin.

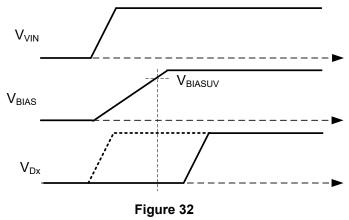
This delay is not required for internal PWM with FSET connected to GND through frequency setting resistor. This is also not needed if the FULL pin remains low.

Faults do not latch; the part recovers when a fault is removed. But if multiple faults occur at the same instance, then part may latch.



Recommendation For When Two Separate Supplies Are Used To Supply the IC VIN Pin and the LED String

In case the LED string and the IC VIN pin are supplied by two separate supplies, the user shall properly size the startup of the LED string supply to guarantee a voltage transition on the IC Dx pins either before or after the BIAS voltage rises up, as showed in the following timing diagram:





High-Current Four-Channel Automotive LED Controller

Quick Summary of Operation

- 1. Internal PWM mode is selected when the FSET pin is connected to GND through a frequency setting resistor.
- 2. External PWM mode is selected when the FSET pin is connected to VBIAS.
- 3. Full mode is selected when the FULL pin is high, and the A80804 operates with 100% duty cycle regardless of internal or external PWM configuration.
- 4. Individual LED current is set by a current sense resistor from the Sx pin to GND for each channel. This current can be derated with analog dimming.
- 5. The voltage on each ADIMx pin sets the peak LED current. Analog dimming for each ADIMx pin is disabled if the ADIMx pin is connected to VBIAS.
- 6. Input voltage derating reduces LED current, similar to analog dimming, when $V_{IN} > 10 \times V_{INDERAT} + 0.7 \text{ V}$ or $V_{IN} > 35 \text{ V}$.
- 7. Internal thermal derating reduces LED current when the A80804 experiences high junction temperatures.
- 8. Open LED fault is disabled when V_{IN} < 5 × V_{FDIS}, where V_{FDIS} is the voltage on FDIS pin. This voltage is usually set by a voltage divider between VBIAS and GND.
- Input undervoltage fault threshold is set by 5 × V_{UVLO}, where V_{UVLO} is the voltage on the UVLO pin. This voltage is usually set by a voltage divider between VBIAS and GND.
- 10. Faults are detected only on enabled channels.
- 11. Faults are only detected when PWMINx is high. During PWM low state the fault state is retained. All four channels can control the nFAULT pin. The nFAULT pin is released if the faulted LED string's PWMINx pin is pulled low for at least 20 ms, allowing faults on other pins to be detected.
- 12. All unused channels must have the PWMINx pin held low.
- 13. Pulling the MODE pin high sets the fault response action to "one-out-all-out", and pulling the MODE pin low sets "one-out-continue (N-1)" mode, where all other LED strings without a fault continue operating. When the MODE pin is high, the nFAULT pin acts as bidirectional fault pin, where multiple A80804 devices can react to a fault together.



PACKAGE OUTLINE DRAWING

For Reference Only – Not for Tooling Use

(Reference JEDEC MO-220VHHD-6)
Dimensions in millimeters – NOT TO SCALE
Exact case and lead configuration at supplier discretion within limits shown

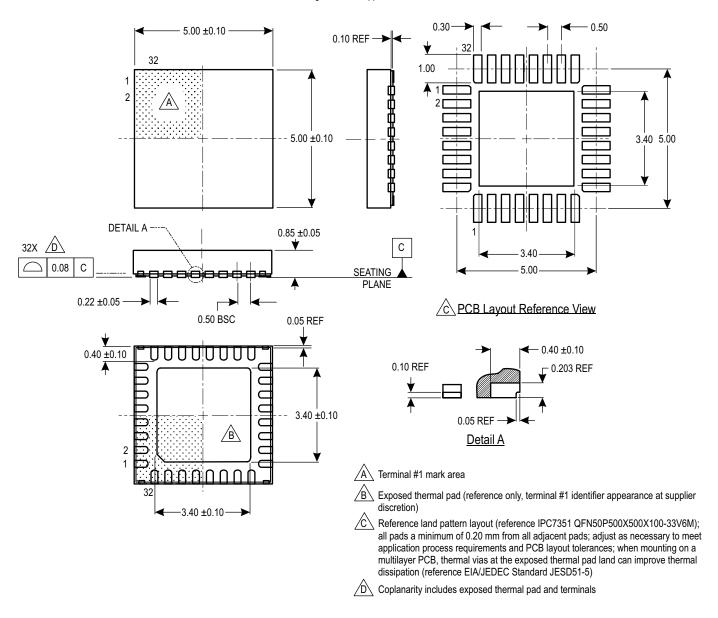


Figure 33: 32-Pin 5 mm × 5 mm QFN with exposed thermal pad and wettable flank (suffix ET)

High-Current Four-Channel Automotive LED Controller

Revision History

Number	Date	Description
_	September 14, 2021	Initial release
1	January 18, 2024	Added Latching Faults table (page 20); updated LED Binning and NTC Derating section (pages 29-30) and Quick Summary of Operation (page 33), and minor editorial updates.
2	October 17, 2024	Updated packing information in selection guide table (page 2); added Source Shorted to GND fault to Tables 1-3 (pages 18-20); minor editorial updates.
3	March 26, 2025	Added "Recommendation for When Two Separate Supplies" section (page 34)

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