

#### **FEATURES AND BENEFITS**

• Integrated contact current sensing for low to medium current ranges:

 $\begin{array}{cccc} \square \ 0 \ to \ 20 \ A & \qquad \square \ 0 \ to \ 50 \ A \\ \square \ \pm 20 \ A & \qquad \square \ \pm 50 \ A \\ \square \ 0 \ to \ 30 \ A & \qquad \square \ 0 \ to \ 65 \ A \\ \square \ \pm 30 \ A & \qquad \square \ \pm 65 \ A \end{array}$ 

- Integrated current carrying conductor (CCC)
- · Linear analog output voltage
- Total error output  $\leq \pm 1.0\%$  FS
- 1 MHz bandwidth
- Response time: ~300 ns
- UL/IEC 62368-1 and UL1577 certification
  - ☐ Rated isolation voltage: 4 kV<sub>RMS</sub>
- □ Working voltage for basic isolation: 701 V<sub>RMS</sub>
- □ Working voltage for reinforced isolation: 344 V<sub>RMS</sub>
- IEC 61000-4-5 certified
- Low noise: 9.5 to 19.0 mA<sub>RMS</sub> @  $f_{BW} = 100 \text{ kHz}$
- Supply voltage: 3.0 to 3.6 V
- Filter function to reduce noise on output pin
- Immunity to common mode fields: -54 dB
- · AEC-Q100 grade 1
- 8-lead SOIC package





#### **DESCRIPTION**

The CT426 is a high bandwidth and ultra-low noise integrated contact current sensor that uses Allegro patented XtremeSense<sup>TM</sup> TMR technology to enable high accuracy current measurements for many consumer, enterprise, and industrial applications. The device supports eight current ranges where the integrated current carrying conductor (CCC) will handle up to 65 A of current and generates a current measurement as a linear analog output voltage. The device achieves a total output error of less than  $\pm 1.0\%$  full-scale (FS).

The device has a  $\sim$ 300 ns output response time while the current consumption is  $\sim$ 6.0 mA and is immune to common mode fields. The CT426 has a filter function to reduce the noise on the output pin.

The CT426 is offered in an industry-standard 8-lead SOIC package that is green and RoHS compliant.

#### **APPLICATIONS**

- Solar/power inverters
- UPS, SMPS, and telecom power supplies
- Motor control
- Power utility meter
- Overcurrent fault protection

#### PACKAGE:



Not to scale

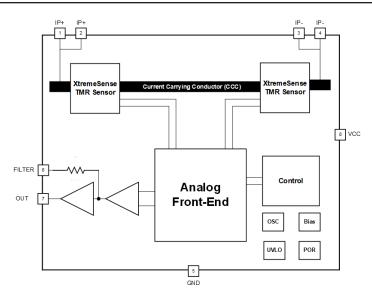


Figure 1: CT426 Functional Block Diagram for 8-Lead SOIC Package

### **CT426**

# XtremeSense™ TMR Current Sensor with Ultra-Low Noise and <0.7% Total Error

#### **SELECTION GUIDE**

Part Number	Current Range (I <sub>PMAX</sub> ) (A)	Sensitivity (mV/A)	Operating Temperature Range (°C)		Packing
CT426-HSN820MR	±20	50			
CT426-HSN830MR	±30	33.3			
CT426-HSN850MR	±50	20			
CT426-HSN865MR	±65	15.4	–40 to 125	8-lead SOIC 4.89 mm × 6.00 mm × 1.62 mm	Tape and
CT426-HSN820DR	20	100	<u>-40 to 125</u>	4.09 11111 * 0.00 111111 * 1.02 111111	Reel
CT426-HSN830DR	30	66.7			
CT426-HSN850DR	50	40			
CT426-HSN865DR	65	30.8			
AEC-Q100 GRADE 1					
CT426-ASN820MR	±20	50			
CT426-ASN830MR	±30	33.3			
CT426-ASN850MR	±50	20			
CT426-ASN865MR	±65	15.4	Grade 1	8-lead SOIC	Tape and
CT426-ASN820DR	20	100	-40 to 125	4.89 mm × 6.00 mm × 1.62 mm	Reel
CT426-ASN830DR	30	66.7			
CT426-ASN850DR	50	40			
CT426-ASN865DR	65	30.8			

#### **EVALUATION BOARD SELECTION GUIDE**

Part Number	Current Range (A)	Operating Temperature Range (°C)
CTD426-20DC	0 to 20	
CTD426-20AC	±20	
CTD426-30DC	0 to 30	
CTD426-30AC	±30	-40 to 125
CTD426-50DC	0 to 50	-40 to 125
CTD426-50AC	±50	
CTD426-65DC	0 to 65	
CTD426-65AC	±65	

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#### **ABSOLUTE MAXIMUM RATINGS** [1]

Characteristic	Symbol	Notes	Rating	Unit
Supply Voltage Strength	V <sub>CC</sub>		-0.3 to 6.0	V
Analog Input/Output Pins Maximum Voltage	V <sub>I/O</sub>		-0.3 to V <sub>CC</sub> + 0.3 <sup>[2]</sup>	V
Current Carrying Conductor Maximum Current	I <sub>CCC(MAX)</sub>	T <sub>A</sub> = 25°C	70	Α
Dielectric Surge Strength Test Voltage	V <sub>SURGE</sub>	IEC 61000-4-5: Tested ±5 Pulses at 2/60 seconds, 1.2 µs (rise) and 50 µs (width)	6.0 (min)	kV
Surge Strength Test Current	I <sub>SURGE</sub>	Tested ±5 Pulses at 3/60 seconds, 8.0 µs (rise) and 20 µs (width)	3.0 (min)	kA
Floatroctatic Discharge Protection Level	ESD	Human Body Model (HBM) per JESD22-A114	±2.0	kV
Electrostatic Discharge Protection Level	ESD	Charged Device Model (CDM) per JESD22-C101	±0.5	kV
Junction Temperature	$T_J$		-40 to 150	°C
Storage Temperature	T <sub>STG</sub>		-65 to 155	°C
Lead Soldering Temperature	T <sub>L</sub>	10 seconds	260	°C

<sup>[1]</sup> Stresses exceeding the absolute maximum ratings may damage the CT426 and may not function or be operable above the recommended operating conditions and stressing the parts to these levels is not recommended. In addition, extended exposure to stresses above the recommended operating conditions may affect device reliability. The absolute maximum ratings are stress ratings only.

#### **RECOMMENDED OPERATING CONDITIONS** [1]

Characteristic	Symbol	Notes	Min.	Тур.	Max.	Unit
Supply Voltage Range	V <sub>CC</sub>		3.0	3.3	3.6	V
Output Voltage Range	V <sub>OUT</sub>		0	_	V <sub>CC</sub>	V
Output Current	I <sub>OUT</sub>		_	_	±1.0	mA
Operating Ambient Temperature	T <sub>A</sub>	Extended Industrial	-40	25	125	°C
		Automotive	-40	25	125	°C

<sup>[1]</sup> The Recommended Operating Conditions table defines the conditions for actual operation of the CT426. Recommended operating conditions are specified to ensure optimal performance to the specifications. Allegro does not recommend exceeding them or designing to absolute maximum ratings.

#### THERMAL CHARACTERISTICS

Characteristic	Symbol	Test Conditions	Value	Unit
Junction-to-Ambient Thermal Resistance	$R_{\thetaJA}$	Junction-to-ambient thermal resistance is a function of application and board layout and is determined in accordance to JEDEC standard JESD51 for a four (4) layer 2s2p FR-4 printed circuit board (PCB) with 2 oz. of copper (Cu) and 4 oz. of copper (Cu) or more for 65 A. Special attention must be paid not to exceed junction temperature T <sub>J(MAX)</sub> at a given ambient temperature T <sub>A</sub> .	25	°C/W
Junction-to-Case Thermal Resistance	$R_{\theta JC}$		15	°C/W



 $<sup>^{[2]}\,\</sup>text{The lower of}\,\text{V}_{\text{CC}}$  + 0.3 V or 6.0 V.

#### **ISOLATION RATINGS**

Characteristic	Symbol	Notes	Rating	Unit
Rated Isolation Voltage	V	Agency Tested per IEC 62368 [1] for 60 seconds. Production Tested at V <sub>ISO</sub> for 1 second per IEC 62368.	4.0	kV <sub>RMS</sub>
	V <sub>ISO</sub>	Agency Tested per UL1577 for 60 seconds. Production Tested at V <sub>ISO</sub> for 1 second per UL1577.	4.0	kV <sub>RMS</sub>
Marking Valtage for Regio legistion	V	Tested per IEC 62368 [1].	991	V <sub>PK</sub>
Working Voltage for Basic Isolation	V <sub>work_iso</sub>	rested per IEC 02300 th.	701	V <sub>RMS</sub>
Working Voltage for Reinforced Isolation	\/	Tested per IEC 62368 [1].	487	V <sub>PK</sub>
Working voltage for Reinforced Isolation	V <sub>WORK_RI</sub>	rested per IEC 02300 th.	344	V <sub>RMS</sub>
Creepage Distance	Creepage Distance D <sub>CR</sub> Minimum distance along package body from IP pins to I/v pins.		4.96	mm
Clearance Distance	D <sub>CL</sub>	Minimum distance through air from IP pins to I/O pins.	4.63	mm
Distance Through Isolation	D <sub>ISO</sub>	Minimum internal distance through isolation	110	μm
Comparative Tracking Index	CTI	Material Group II	400 to 599	V

<sup>[1]</sup> IEC 62368 is the succeeding standard to IEC 60950-1 (Edition 2) for isolation testing specifications and as such it will be compliant to the latter standard.

### **APPLICATION DIAGRAM**

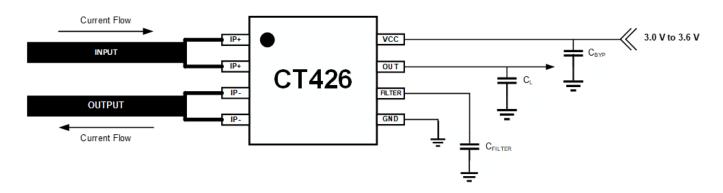


Figure 2: CT426 Application Block Diagram

**Table 1: Recommended External Components** 

Component	Description	Vendor and Part Number	Min.	Тур.	Max.	Unit
C <sub>BYP</sub>	1.0 µF, X5R or Better	Murata GRM155C81A105KA12	_	1.0	_	μF
C <sub>FILTER</sub>	Various, X5R or Better	Murata	_	See Figure 35	_	nF



### PINOUT DIAGRAM AND TERMINAL LIST

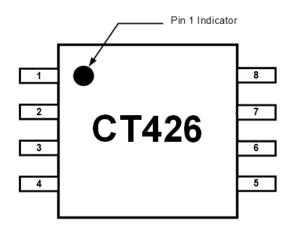


Figure 3: CT426 Pinout Diagram for 8-lead SOIC Package (Top-Down View)

#### **Terminal List**

Number	Name	Function
1, 2	IP+	Input primary conductor (positive).
3, 4	IP-	Output primary conductor (negative).
5	GND	Ground.
6	FILTER	Filter pin to improve noise performance by connecting an external capacitor to set the cut-off frequency.  No connect if the FILTER pin is not used.
7	OUT	Analog output voltage that represents the measured current.
8	VCC	Supply voltage.



**ELECTRICAL CHARACTERISTICS:** Valid for  $V_{CC}$  = 3.0 to 3.6 V,  $C_{BYP}$  = 1.0  $\mu$ F, and  $T_A$  = -40°C to 125°C, typical values are  $V_{CC}$  = 3.3 V and  $T_A$  = 25°C, unless otherwise specified

Characteristics	Symbol	Test Conditions	Min.	Тур.	Max.	Unit		
POWER SUPPLIES								
Supply Current	$I_{CC}$	f <sub>BW</sub> = 1 MHz, no load, I <sub>P</sub> = 0 A	_	6.0	9.0	mA		
OUT Maximum Drive Capability [1]	I <sub>OUT</sub>	OUT covers 10% to 90% of V <sub>CC</sub> span	-1.0	-	+1.0	mA		
OUT Capacitive Load [1]	C <sub>L_OUT</sub>		-	-	100	pF		
OUT Resistive Load [1]	$R_{L\_OUT}$		_	100	_	kΩ		
Primary Conductor Resistance [1]	R <sub>IP</sub>		_	0.5	_	mΩ		
Power Supply Rejection Ratio [1]	PSRR		_	35	_	dB		
Sensitivity Power Supply Rejection Ratio [1]	SPSRR		_	35	-	dB		
Offset Power Supply Rejection Ratio [1]	OPSRR		_	40	_	dB		
ANALOG OUTPUT (OUT)			`					
OUT Voltage Linear Range, Typical	V <sub>OUT</sub>	V <sub>SIG_AC</sub> = ±1.00 V, V <sub>SIG_DC</sub> = +2.00 V	0.65	-	2.65	V		
Output High Saturation Voltage	V <sub>OUT_SAT</sub>	V <sub>OUT</sub> , T <sub>A</sub> = 25°C	V <sub>CC</sub> - 0.30	V <sub>CC</sub> - 0.25	_	V		
Common Made Field Dejection Datio [1]	CMFRR		_	-54	_	dB		
Common Mode Field Rejection Ratio [1]			_	0.5	_	mA/G		
TIMINGS								
Power-On Time [1]	t <sub>ON</sub>	V <sub>CC</sub> ≥ 2.50 V	_	100	200	μs		
Rise Time [1]	t <sub>RISE</sub>	$I_P = I_{RANGE(MAX)}, T_A = 25^{\circ}C, C_L = 220 pF$	_	200	_	ns		
Response Time [1]	t <sub>RESPONSE</sub>	$I_P = I_{RANGE(MAX)}$ , $T_A = 25$ °C, $C_L = 220$ pF	_	300	-	ns		
Propagation Delay [1]	t <sub>DELAY</sub>	$I_P = I_{RANGE(MAX)}, T_A = 25^{\circ}C, C_L = 220 pF$	_	250	_	ns		
PROTECTION								
Undervoltage Lockout	\ <u>'</u>	Rising V <sub>DD</sub>	_	2.50	_	V		
Officer voltage Lockout	$V_{UVLO}$	Falling V <sub>DD</sub>	_	2.45	_	V		
UVLO Hysteresis	V <sub>UV_HYS</sub>		_	50	_	mV		

 $<sup>\</sup>ensuremath{^{[1]}}$  Guaranteed by design and characterization; not tested in production.



#### **ELECTRICAL CHARACTERISTICS**

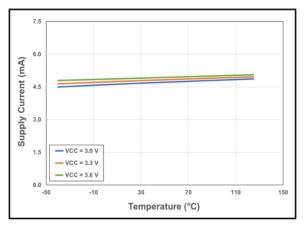


Figure 4: CT426 Supply Current vs. Temperature vs. Supply Voltage

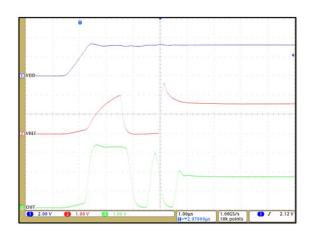


Figure 5: CT426 Startup Waveforms for  $V_{OQ} = 1.65 V$  (AC Current)

### ELECTRICAL CHARACTERISTICS (continued) $V_{CC}$ = 3.3 V, $T_A$ = 25°C, and $C_{BYP}$ = 1.0 $\mu$ F (unless otherwise specified)

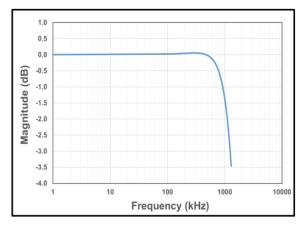


Figure 6: CT426 Bandwidth with  $C_{FILTER} = 1.0 pF$ 

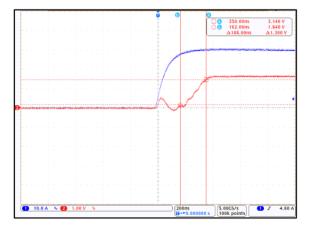


Figure 8: CT426 Rise Time;  $I_P = 30 A_{PK}$  and  $C_L = 100 pF$ 

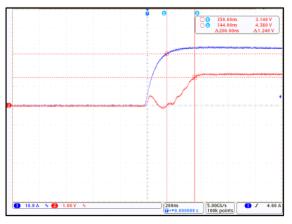


Figure 7: CT426 Response Time;  $I_P = 30 A_{PK}$ and  $C_L = 100 pF$ 

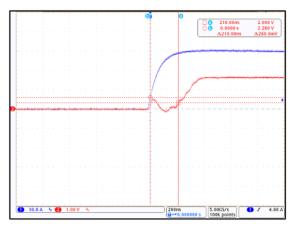


Figure 9: CT426 Propagation Delay;  $I_P$  = 30  $A_{PK}$  and  $C_L$  = 100 pF



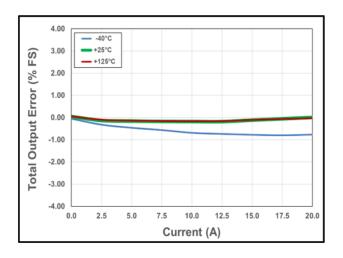
CT426-xSN820DR: 0 to 20 A – ELECTRICAL CHARACTERISTICS: Valid for  $V_{CC}$  = 3.0 to 3.6 V,  $C_{BYP}$  = 1.0  $\mu$ F, and  $T_A$  =  $-40^{\circ}$ C to 125°C, typical values are  $V_{CC}$  = 3.3 V and  $T_A$  = 25°C, unless otherwise specified

Characteristics	Symbol	Test Conditions	Min.	Тур.	Max.	Unit	
Current Range	I <sub>RANGE</sub>		0	_	20	Α	
Voltage Output Quiescent	V <sub>OQ</sub>	T <sub>A</sub> = 25°C, I <sub>P</sub> = 0 A	0.645	0.650	0.655	V	
Sensitivity	S	$I_{RANGE(MIN)} < I_{P} < I_{RANGE(MAX)}$	_	100	_	mV/A	
Bandwidth [1]	f <sub>BW</sub>	Small Signal = –3 dB	_	1.0	_	MHz	
Noise [1]	e <sub>N</sub>	T <sub>A</sub> = 25°C, f <sub>BW</sub> = 100 kHz	_	9.5	_	mA <sub>RMS</sub>	
OUT ACCURACY PERFORMANCE			·				
Total Output Error	E <sub>OUT</sub>	$I_P = I_{P(MAX)}$	_	±0.7	±1.0	% FS	
Non-Linearity Error [1]	E <sub>LIN</sub>	$I_P = I_{P(MAX)}, T_A = -40^{\circ}C \text{ to } 125^{\circ}C$	_	±0.1	_	% FS	
Sensitivity Error [1]	E <sub>SENS</sub>	$I_P = I_{P(MAX)}, T_A = -40^{\circ}C \text{ to } 125^{\circ}C$	_	±0.2	_	% FS	
Office 4 ) / 1   1   1   1   1   1   1   1   1   1		T 0.4 T 40°0 t 40°0	_	±5.2	_	mV	
Offset Voltage [1]	V <sub>OFFSET</sub>	$I_P = 0 \text{ A}, T_A = -40^{\circ}\text{C to } 125^{\circ}\text{C}$	_	±0.3	_	% FS	
LIFETIME DRIFT							
Total Output Error Lifetime Drift [1]	E <sub>TOT_DRIFT</sub>	$I_P = I_{P(MAX)}$	_	±1.0	_	% FS	

<sup>[1]</sup> Guaranteed by design and characterization; not tested in production.



#### **ELECTRICAL CHARACTERISTICS FOR CT426-xSN820DR**



1.00E+09

1.00E+09

1.00E+07

1.00E+04

1.00E+04

1.00E+02

1.00E+03

1.00E+04

1.00E+05

Frequency (Hz)

Figure 10: Total Output Error vs. Current vs. Temperature

Figure 11: Noise Density vs. Frequency

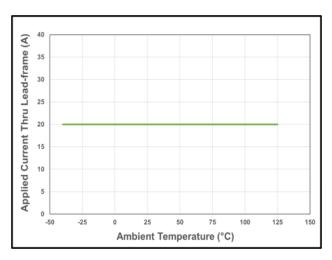


Figure 12: CT426 Current Derating Curve for 20 A<sub>DC</sub>



CT426-xSN820MR:  $\pm 20$  A - ELECTRICAL CHARACTERISTICS: Valid for  $V_{CC}$  = 3.0 to 3.6 V,  $C_{BYP}$  = 1.0  $\mu$ F, and  $T_A$  =  $-40^{\circ}$ C to 125°C, typical values are  $V_{CC}$  = 3.3 V and  $T_A$  = 25°C, unless otherwise specified

Characteristics	Symbol	Test Conditions	Min.	Тур.	Max.	Unit
Current Range	I <sub>RANGE</sub>		-20	_	20	Α
Voltage Output Quiescent	V <sub>OQ</sub>	T <sub>A</sub> = 25°C, I <sub>P</sub> = 0 A	1.645	1.650	1.655	V
Sensitivity	S	$I_{RANGE(MIN)} < I_{P} < I_{RANGE(MAX)}$	-	50	-	mV/A
Bandwidth [1]	f <sub>BW</sub>	Small Signal = -3 dB	-	1.0	_	MHz
Noise [1]	e <sub>N</sub>	T <sub>A</sub> = 25°C, f <sub>BW</sub> = 100 kHz	-	11.0	_	mA <sub>RMS</sub>
OUT ACCURACY PERFORMANCE	,					
Total Output Error	E <sub>OUT</sub>	$I_{P} = I_{P(MAX)}$	_	±0.5	±1.0	% FS
Non-Linearity Error [1]	E <sub>LIN</sub>	$I_P = I_{P(MAX)}, T_A = -40^{\circ}C \text{ to } 125^{\circ}C$	-	±0.1	_	% FS
Sensitivity Error [1]	E <sub>SENS</sub>	$I_P = I_{P(MAX)}, T_A = -40^{\circ}C \text{ to } 125^{\circ}C$	-	±0.3	_	% FS
Office 4 \ / =  4 =   =   [1]	.,	T = 0.4 T = 40°C to 40°C	-	±7.9	_	mV
Offset Voltage [1]	V <sub>OFFSET</sub>	$I_P = 0 \text{ A}, T_A = -40^{\circ}\text{C to } 125^{\circ}\text{C}$	_	±0.4	_	% FS
LIFETIME DRIFT						
Total Output Error Lifetime Drift [1]	E <sub>TOT_DRIFT</sub>	$I_{P} = I_{P(MAX)}$	_	±1.0	_	% FS

 $<sup>\</sup>ensuremath{^{[1]}}$  Guaranteed by design and characterization; not tested in production.



#### **ELECTRICAL CHARACTERISTICS FOR CT426-xSN820MR**

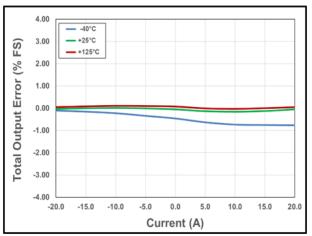


Figure 13: Total Output Error vs. Current vs.
Temperature

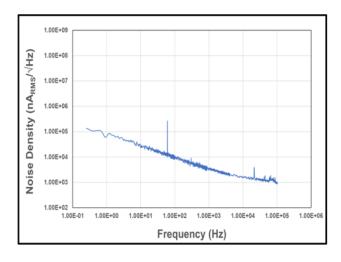


Figure 14: Noise Density vs. Frequency

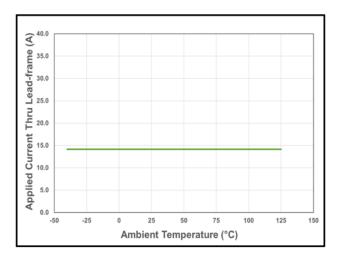


Figure 15: CT426 Current Derating Curve for 20  $A_{PK}$  (14.1  $A_{DC}$ )



CT426-xSN830DR: 0 to 30 A – ELECTRICAL CHARACTERISTICS: Valid for  $V_{CC}$  = 3.0 to 3.6 V,  $C_{BYP}$  = 1.0  $\mu$ F, and  $T_A$  =  $-40^{\circ}$ C to 125°C, typical values are  $V_{CC}$  = 3.3 V and  $T_A$  = 25°C, unless otherwise specified

Characteristics	Symbol	Test Conditions	Min.	Тур.	Max.	Unit
Current Range	I <sub>RANGE</sub>		0	_	30	А
Voltage Output Quiescent	V <sub>OQ</sub>	T <sub>A</sub> = 25°C, I <sub>P</sub> = 0 A	0.645	0.650	0.655	V
Sensitivity	S	$I_{RANGE(MIN)} < I_{P} < I_{RANGE(MAX)}$	_	66.7	-	mV/A
Bandwidth [1]	f <sub>BW</sub>	Small Signal = –3 dB, C <sub>FILTER</sub> = 5 pF	_	1.0	-	MHz
Noise [1]	e <sub>N</sub>	T <sub>A</sub> = 25°C, f <sub>BW</sub> = 100 kHz	_	10.0	-	mA <sub>RMS</sub>
OUT ACCURACY PERFORMANCE					`	
Total Output Error	E <sub>OUT</sub>	$I_{P} = I_{P(MAX)}$	_	±0.7	±1.0	% FS
Non-Linearity Error [1]	E <sub>LIN</sub>	$I_P = I_{P(MAX)}, T_A = -40^{\circ}C \text{ to } 125^{\circ}C$	_	±0.1	_	% FS
Sensitivity Error [1]	E <sub>SENS</sub>	$I_P = I_{P(MAX)}, T_A = -40^{\circ}C \text{ to } 125^{\circ}C$	_	±0.3	_	% FS
Office 4 V (214 cm c [1])		T 0 A T 40°0 to 40°0	_	±4.4	_	mV
Offset Voltage [1]	V <sub>OFFSET</sub>	$I_P = 0 \text{ A}, T_A = -40^{\circ}\text{C to } 125^{\circ}\text{C}$	_	±0.2	_	% FS
LIFETIME DRIFT			,			
Total Output Error Lifetime Drift [1]	E <sub>TOT_DRIFT</sub>	$I_{P} = I_{P(MAX)}$	_	±1.0	_	% FS

 $<sup>\</sup>ensuremath{^{[1]}}$  Guaranteed by design and characterization; not tested in production.



#### **ELECTRICAL CHARACTERISTICS FOR CT426-xSN830DR**

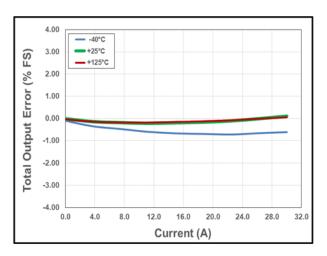


Figure 16: Total Output Error vs. Current vs. Temperature

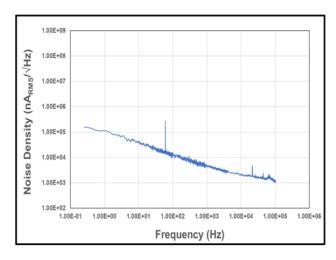


Figure 17: Noise Density vs. Frequency

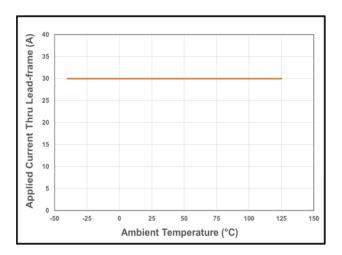


Figure 18: CT426 Current Derating Curve for 30 A<sub>DC</sub>



CT426-xSN830MR:  $\pm 30$  A - ELECTRICAL CHARACTERISTICS: Valid for  $V_{CC}$  = 3.0 to 3.6 V,  $C_{BYP}$  = 1.0  $\mu$ F, and  $T_A$  =  $-40^{\circ}$ C to 125°C, typical values are  $V_{CC}$  = 3.3 V and  $T_A$  = 25°C, unless otherwise specified

Characteristics	Symbol	Test Conditions	Min.	Тур.	Max.	Unit
Current Range	I <sub>RANGE</sub>		-30	-	30	Α
Voltage Output Quiescent	V <sub>OQ</sub>	T <sub>A</sub> = 25°C, I <sub>P</sub> = 0 A	1.645	1.650	1.655	V
Sensitivity	S	$I_{RANGE(MIN)} < I_{P} < I_{RANGE(MAX)}$	_	33.3	-	mV/A
Bandwidth [1]	f <sub>BW</sub>	Small Signal = –3 dB, C <sub>FILTER</sub> = 5 pF	_	1.0	_	MHz
Noise [1]	e <sub>N</sub>	T <sub>A</sub> = 25°C, f <sub>BW</sub> = 100 kHz	_	12.5	_	mA <sub>RMS</sub>
OUT ACCURACY PERFORMANCE				`	`	
Total Output Error	E <sub>OUT</sub>	$I_P = I_{P(MAX)}$	_	±0.5	±1.0	% FS
Non-Linearity Error [1]	E <sub>LIN</sub>	$I_P = I_{P(MAX)}, T_A = -40^{\circ}C \text{ to } 125^{\circ}C$	_	±0.1	_	% FS
Sensitivity Error [1]	E <sub>SENS</sub>	$I_P = I_{P(MAX)}, T_A = -40^{\circ}C \text{ to } 125^{\circ}C$	_	±0.3	_	% FS
Off - 4 \ / -   4 [1]	1	T = 0 A T = 40°C t= 405°C	_	±6.6	_	mV
Offset Voltage [1]	V <sub>OFFSET</sub>	$I_P = 0 \text{ A}, T_A = -40^{\circ}\text{C to } 125^{\circ}\text{C}$	_	±0.3	_	% FS
LIFETIME DRIFT						
Total Output Error Lifetime Drift [1]	E <sub>TOT_DRIFT</sub>	$I_P = I_{P(MAX)}$	_	±1.0	_	% FS

<sup>[1]</sup> Guaranteed by design and characterization; not tested in production.



#### **ELECTRICAL CHARACTERISTICS FOR CT426-xSN830MR**

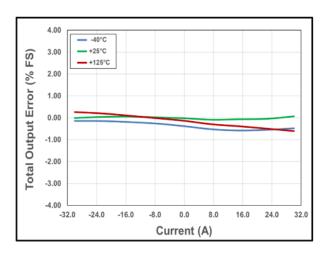


Figure 19: Total Output Error vs. Current vs. Temperature

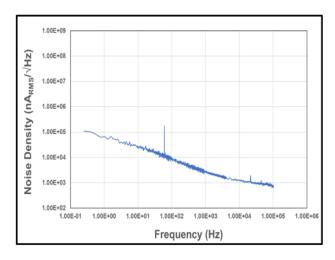


Figure 20: Noise Density vs. Frequency

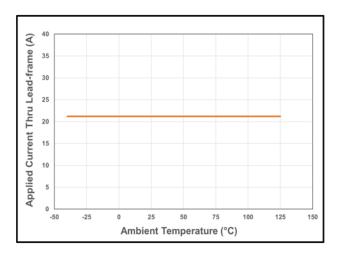


Figure 21: CT426 Current Derating Curve for 30  $A_{PK}$  (21.2  $A_{DC}$ )



CT426-xSN850DR: 0 to 50 A – ELECTRICAL CHARACTERISTICS: Valid for  $V_{CC}$  = 3.0 to 3.6 V,  $C_{BYP}$  = 1.0  $\mu$ F, and  $T_A$  =  $-40^{\circ}$ C to 125°C, typical values are  $V_{CC}$  = 3.3 V and  $T_A$  = 25°C, unless otherwise specified

Characteristics	Symbol	Test Conditions	Min.	Тур.	Max.	Unit
Current Range	I <sub>RANGE</sub>		0	_	50	А
Voltage Output Quiescent	V <sub>OQ</sub>	T <sub>A</sub> = 25°C, I <sub>P</sub> = 0 A	0.645	0.650	0.655	V
Sensitivity	S	$I_{RANGE(MIN)} < I_{P} < I_{RANGE(MAX)}$	_	40	_	mV/A
Bandwidth [1]	f <sub>BW</sub>	Small Signal = -3 dB	_	1.0	_	MHz
Noise [1]	e <sub>N</sub>	T <sub>A</sub> = 25°C, f <sub>BW</sub> = 100 kHz	_	11.0	_	mA <sub>RMS</sub>
OUT ACCURACY PERFORMANCE				`		
Total Output Error	E <sub>OUT</sub>	$I_P = I_{P(MAX)}$	_	±1.0	±1.5	% FS
Non-Linearity Error <sup>[1]</sup>	E <sub>LIN</sub>	$I_{P} = I_{P(MAX)}, T_{A} = -40^{\circ}C \text{ to } 125^{\circ}C$	_	±0.2	_	% FS
Sensitivity Error [1]	E <sub>SENS</sub>	$I_{P} = I_{P(MAX)}, T_{A} = -40^{\circ}C \text{ to } 125^{\circ}C$	_	±0.7	_	% FS
Official Violence [1]	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	T = 0.4 T = 40°C t= 405°C	_	±8.8	_	mV
Offset Voltage <sup>[1]</sup>	V <sub>OFFSET</sub>	$I_P = 0 \text{ A}, T_A = -40^{\circ}\text{C} \text{ to } 125^{\circ}\text{C}$	_	±0.4	_	% FS
LIFETIME DRIFT				•		
Total Output Error Lifetime Drift [1]	E <sub>TOT_DRIFT</sub>	$I_P = I_{P(MAX)}$	_	±1.0	_	% FS

 $<sup>\</sup>ensuremath{^{[1]}}$  Guaranteed by design and characterization; not tested in production.



#### **ELECTRICAL CHARACTERISTICS FOR CT426-xSN850DR**

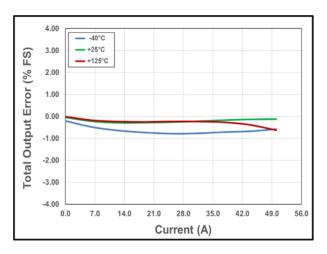


Figure 22: Total Output Error vs. Current vs. Temperature

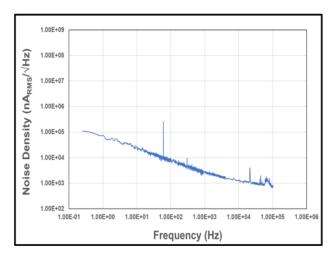


Figure 23: Noise Density vs. Frequency

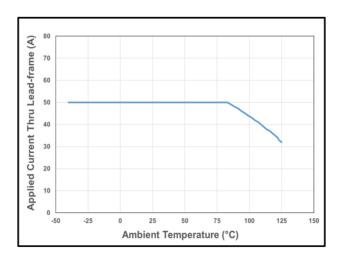


Figure 24: CT426 Current Derating Curve for 50  $A_{DC}$ 



CT426-xSN850MR:  $\pm 50$  A - ELECTRICAL CHARACTERISTICS: Valid for  $V_{CC}$  = 3.0 to 3.6 V,  $C_{BYP}$  = 1.0  $\mu$ F, and  $T_A$  =  $-40^{\circ}$ C to 125°C, typical values are  $V_{CC}$  = 3.3 V and  $T_A$  = 25°C, unless otherwise specified

Characteristics	Symbol	Test Conditions	Min.	Тур.	Max.	Unit
Current Range	I <sub>RANGE</sub>		-50	_	50	А
Voltage Output Quiescent	V <sub>OQ</sub>	T <sub>A</sub> = 25°C, I <sub>P</sub> = 0 A	1.645	1.650	1.655	V
Sensitivity	S	$I_{RANGE(MIN)} < I_{P} < I_{RANGE(MAX)}$	_	20	-	mV/A
Bandwidth [1]	f <sub>BW</sub>	Small Signal = -3 dB	_	1.0	-	MHz
Noise [1]	e <sub>N</sub>	T <sub>A</sub> = 25°C, f <sub>BW</sub> = 100 kHz	_	19.0	-	mA <sub>RMS</sub>
OUT ACCURACY PERFORMANCE						
Total Output Error	E <sub>OUT</sub>	$I_P = I_{P(MAX)}$	_	±0.5	±1.0	% FS
Non-Linearity Error [1]	E <sub>LIN</sub>	$I_P = I_{P(MAX)}$ , $T_A = -40$ °C to 125°C	_	±0.1	_	% FS
Sensitivity Error [1]	E <sub>SENS</sub>	$I_P = I_{P(MAX)}, T_A = -40^{\circ}C \text{ to } 125^{\circ}C$	_	±0.5	-	% FS
Off - + \ / -   1 [1]	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	T = 0.0 T = 40°C to 405°C	_	±6.0	-	mV
Offset Voltage [1]	V <sub>OFFSET</sub>	$I_P = 0 \text{ A}, T_A = -40^{\circ}\text{C to } 125^{\circ}\text{C}$	_	±0.3	_	% FS
LIFETIME DRIFT	•					•
Total Output Error Lifetime Drift [1]	E <sub>TOT_DRIFT</sub>	$I_P = I_{P(MAX)}$	_	±1.0	_	% FS

 $<sup>\</sup>ensuremath{^{[1]}}$  Guaranteed by design and characterization; not tested in production.



#### **ELECTRICAL CHARACTERISTICS FOR CT426-xSN850MR**

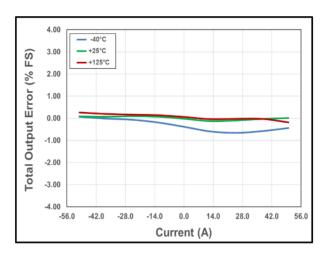


Figure 25: Total Output Error vs. Current vs. Temperature

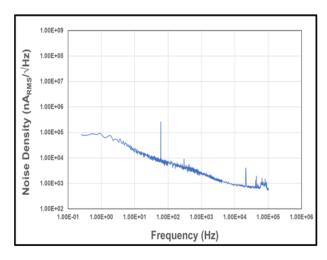


Figure 26: Noise Density vs. Frequency

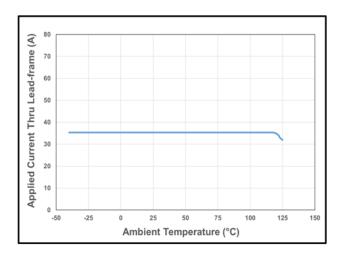


Figure 27: CT426 Current Derating Curve for 50  $A_{PK}$  (35.4  $A_{DC}$ )



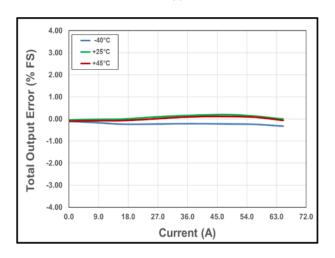
CT426-xSN865DR: 0 to 65 A – ELECTRICAL CHARACTERISTICS: Valid for  $V_{CC}$  = 3.0 to 3.6 V,  $C_{BYP}$  = 1.0  $\mu$ F, and  $T_A$  =  $-40^{\circ}$ C to 125°C, typical values are  $V_{CC}$  = 3.3 V and  $T_A$  = 25°C, unless otherwise specified

Characteristics	Symbol	Test Conditions	Min.	Тур.	Max.	Unit
Current Range	I <sub>RANGE</sub>		0	_	65	А
Voltage Output Quiescent	V <sub>OQ</sub>	T <sub>A</sub> = 25°C, I <sub>P</sub> = 0 A	0.645	0.650	0.655	V
Sensitivity	S	I <sub>RANGE(MIN)</sub> < I <sub>P</sub> < I <sub>RANGE(MAX)</sub>	_	30.8	_	mV/A
Bandwidth [1]	f <sub>BW</sub>	Small Signal = –3 dB, C <sub>FILTER</sub> = 5 pF	_	1.0	_	MHz
Noise [1]	e <sub>N</sub>	T <sub>A</sub> = 25°C, f <sub>BW</sub> = 100 kHz	_	11.5	_	mA <sub>RMS</sub>
OUT ACCURACY PERFORMANCE	·			`		
Total Output Error	E <sub>OUT</sub>	$I_P = I_{P(MAX)}$	_	±1.0	±1.5	% FS
Non-Linearity Error [1]	E <sub>LIN</sub>	$I_P = I_{P(MAX)}, T_A = -40^{\circ}C \text{ to } 125^{\circ}C$	_	±0.2	_	% FS
Sensitivity Error [1]	E <sub>SENS</sub>	$I_P = I_{P(MAX)}, T_A = -40^{\circ}C \text{ to } 125^{\circ}C$	_	±0.2	_	% FS
Office 4 ) / 1   1   1   1   1   1   1   1   1   1	.,	T 0 A T 4000 to 40500	_	±3.0	_	mV
Offset Voltage [1]	V <sub>OFFSET</sub>	$I_P = 0 \text{ A}, T_A = -40^{\circ}\text{C to } 125^{\circ}\text{C}$	_	±0.1	_	% FS
LIFETIME DRIFT	•					
Total Output Error Lifetime Drift [1]	E <sub>TOT_DRIFT</sub>	$I_P = I_{P(MAX)}$	_	±1.0	_	% FS

 $<sup>\</sup>ensuremath{^{[1]}}$  Guaranteed by design and characterization; not tested in production.



### **ELECTRICAL CHARACTERISTICS FOR CT426-xSN865DR**



1.00E+09
1.00E+08
1.00E+07
1.00E+06
1.00E+04
1.00E+03
1.00E+03
1.00E+03
1.00E+04
Frequency (Hz)

Figure 28: Total Output Error vs. Current vs. Temperature

Figure 29: Noise Density vs. Frequency

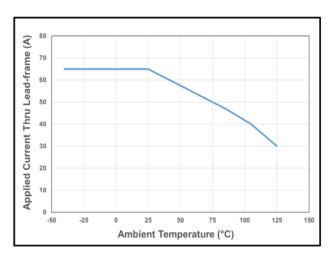


Figure 30: CT426 Current Derating Curve for 65 A<sub>DC</sub>



CT426-xSN865MR:  $\pm 65$  A - ELECTRICAL CHARACTERISTICS: Valid for  $V_{CC}$  = 3.0 to 3.6 V,  $C_{BYP}$  = 1.0  $\mu$ F, and  $T_A$  =  $-40^{\circ}$ C to 125°C, typical values are  $V_{CC}$  = 3.3 V and  $T_A$  = 25°C, unless otherwise specified

Characteristics	Symbol	Test Conditions	Min.	Тур.	Max.	Unit
Current Range	I <sub>RANGE</sub>		-65	_	65	А
Voltage Output Quiescent	V <sub>OQ</sub>	T <sub>A</sub> = 25°C, I <sub>P</sub> = 0 A	1.645	1.650	1.655	V
Sensitivity	S	$I_{RANGE(MIN)} < I_{P} < I_{RANGE(MAX)}$	_	15.4	_	mV/A
Bandwidth [1]	f <sub>BW</sub>	Small Signal = –3 dB, C <sub>FILTER</sub> = 5 pF	_	1.0	_	MHz
Noise [1]	e <sub>N</sub>	T <sub>A</sub> = 25°C, f <sub>BW</sub> = 100 kHz	_	19.0	_	mA <sub>RMS</sub>
OUT ACCURACY PERFORMANCE						
Total Output Error	E <sub>OUT</sub>	$I_P = I_{P(MAX)}$	_	±0.5	±1.0	% FS
Non-Linearity Error <sup>[1]</sup>	E <sub>LIN</sub>	$I_P = I_{P(MAX)}, T_A = -40^{\circ}C \text{ to } 125^{\circ}C$	_	±0.2	_	% FS
Sensitivity Error [1]	E <sub>SENS</sub>	$I_{P} = I_{P(MAX)}, T_{A} = -40^{\circ}C \text{ to } 125^{\circ}C$	_	±0.3	_	% FS
Off - 4 \ / -  4 [1]		T = 0.4 T = 40°C t= 405°C	_	±4.0	_	mV
Offset Voltage [1]	V <sub>OFFSET</sub>	$I_P = 0 \text{ A}, T_A = -40^{\circ}\text{C} \text{ to } 125^{\circ}\text{C}$	_	±0.1	_	% FS
LIFETIME DRIFT	,		•	•	•	
Total Output Error Lifetime Drift [1]	E <sub>TOT_DRIFT</sub>	$I_{P} = I_{P(MAX)}$	_	±1.0	_	% FS

<sup>[1]</sup> Guaranteed by design and characterization; not tested in production.



### **ELECTRICAL CHARACTERISTICS FOR CT426-xSN865MR**

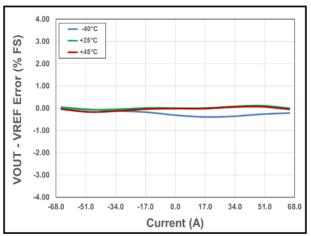


Figure 31: Total Output Error vs. Current vs. Temperature

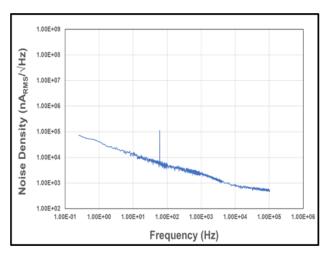


Figure 32: Noise Density vs. Frequency

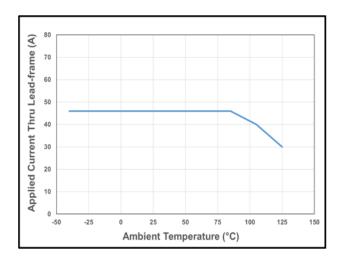


Figure 33: CT426 Current Derating Curve for 65  $A_{PK}$  (46.0  $A_{DC}$ )



#### **FUNCTIONAL DESCRIPTION**

#### Overview

The CT426 is a high accuracy contact current sensor with an integrated current-carrying conductor that handles up to 65 A. It has high sensitivity and a wide dynamic range with excellent accuracy (low total output error) across temperature. This current sensor supports eight current ranges:

• 0 to 50 A

- 0 to 20 A
   ±20 A
   0 to 30 A
  - ±50 A0 to 65 A
- ±30 A
- ±65 A

When current is flowing through the current-carrying conductor, the XtremeSense TMR sensors inside the chip senses the field which in turn generates differential voltage signals that then goes through the Analog Front-End (AFE) to output a current measurement with less than  $\pm 1.0\%$  full-scale total output error (E\_OUT).

The chip is designed to enable a fast response time of 300 ns for the current measurement from the OUT pin as the bandwidth for the CT426 is 1.0 MHz. Even with a high bandwidth, the chip consumes a minimal amount of power.

### **Linear Output Current Measurement**

The CT426 provides a continuous linear analog output voltage which represents the current measurement. The output voltage range of OUT is from 0.65 to 2.65 V with a  $V_{\rm OQ}$  of 0.65 V and 1.65 V for unidirectional and bidirectional currents, respectively. Figure 34 illustrates the output voltage range of the OUT pin as a function of the measured current.

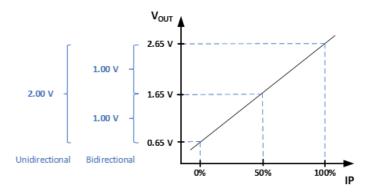


Figure 34: Linear Output Voltage Range (OUT) vs.

Measured Current (IP)

### Filter Function (FILTER)

The CT426 has a pin for the FILTER function which will enable it to improve the noise performance by changing the cutoff frequency. The bandwidth of the CT426 is 1.0 MHz; however, adding a capacitor to the FILTER pin—which will be in-series with an internal resistance of approximately 15 k $\Omega$ —will set the cutoff frequency to reduce noise.

Experimentally measured Bandwidth does not necessarily match the calculated bandwidth value obtained by using the equation  $f_{BW} = \frac{1}{2\pi RC}$  because of the parasitic capacitances due to PCB manufacturing and layout. This is further impacted by the small, picofarad level  $C_{\rm FILTER}$  recommendations.

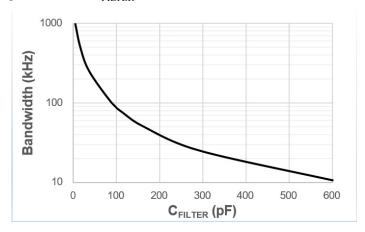


Figure 35: Experimental Bandwidth vs.  $C_{\text{FILTER}}$ Sensitivity

Sensitivity (S) is a change in the CT426 output in response to a change in 1 A of current flowing through the current-carrying conductor. It is defined by the product of the magnetic circuit sensitivity (G/A, where 1.0 G = 0.1 mT) and the chip linear amplifier gain (mV/G). Therefore, the result of this gives a sensitivity unit of mV/A. The CT426 is factory-calibrated to optimize the sensitivity for the full scale of the device dynamic range.

### **Total Output Error**

The Total Output Error  $(E_{OUT})$  is the maximum deviation of the sensor output from the ideal sensor transfer curve over the full temperature range relative to the sensor full scale.

The Total Output Error is measured by performing a full-scale primary current (IP) sweep and measuring V<sub>OUT</sub> at multiple points.



$$E_{OUT} = 100 * \frac{\max(V_{OUT_{IDEAL}}(I) - V_{OUT}(I))}{F.S.}$$

The Ideal Transfer Curve is calculated based on datasheet parameters as described below.

$$V_{OUT_{IDEAL}}(I_P) = V_{OQ} + S * I_P$$

 $E_{OUT}$  incorporates all sources of error and is a function of the sensed current ( $I_P$ ) from the current sensor.

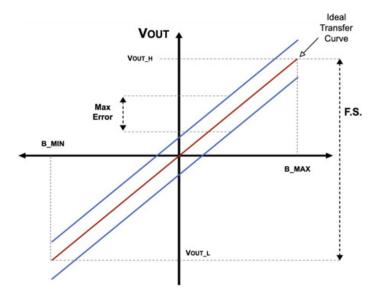


Figure 36: Total Output Error (E<sub>OUT</sub>) vs. Sensed Current (I<sub>P</sub>)

The CT426 achieves a total output error ( $E_{OUT}$ ) that is less than  $\pm 1.0\%$  of Full-Scale (FS) over supply voltage and temperature. It is designed with innovative and proprietary TMR sensors and circuit blocks to provide very accurate current measurements regardless of the operating conditions.

### **Sensitivity Error**

The sensitivity error ( $E_{SENS}$ ) is the sensitivity temperature drift error for unipolar or DC current. It is calculated using the equation below:

$$E_{SENS} = 100 \times \left(\frac{S_{MEASURED}}{S} - 1\right)$$

For bipolar or AC current, the  $E_{\text{SENS}}$  is calculated by dividing the equation by 2.

### Power-On Time (t<sub>ON</sub>)

Power-On Time ( $t_{ON}$ ) of 100  $\mu s$  is the amount of time required by CT426 to start up, fully power the chip, and becoming fully operational from the moment the supply voltage is applied to it. This time includes the ramp-up time and the settling time (within 10% of steady-state voltage under an applied magnetic field) after the power supply has reached the minimum  $V_{CC}$ .

### Response Time (t<sub>RESPONSE</sub>)

Response Time ( $t_{RESPONSE}$ ) of 300 ns for the CT426 is the time interval between the following terms:

- 1. When the primary current signal reaches 90% of its final value,
- 2. When the chip reaches 90% of its output corresponding to the applied current.

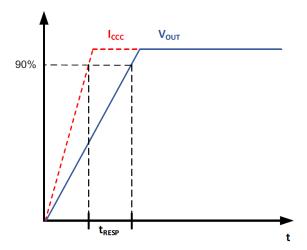


Figure 37: CT426 Response Time Curve

### Rise Time (t<sub>RISE</sub>)

Rise Time ( $t_{RISE}$ ) is the time interval of when it reaches 10% and 90% of the full-scale output voltage. The  $t_{RISE}$  of the CT426 is 200 ns.

### **Propagation Delay (t<sub>DELAY</sub>)**

Propagation Delay (t<sub>DELAY</sub>) is the time difference between these two events:

- 1. When the primary current reaches 20% of its final value
- 2. When the chip reaches 20% of its output corresponding to the applied current.

The CT426 has a propagation delay of 250 ns.



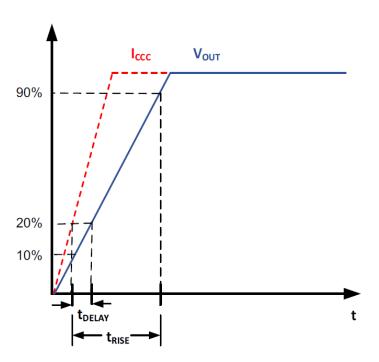


Figure 38: CT426 Propagation Delay and Rise Time Curve

### **Undervoltage Lockout (UVLO)**

The Undervoltage Lockout protection circuitry of the CT426 is activated when the supply voltage ( $V_{CC}$ ) falls below 2.45 V. The CT426 remains in a low quiescent state until  $V_{CC}$  rises above the UVLO threshold (2.50 V). In this condition where  $V_{CC}$  is less than 2.45 V and UVLO is triggered, the output from the CT426 is not valid. Once the VCC rises above 2.50 V then the UVLO is cleared

#### **Immunity to Common Mode Fields**

The CT426 is housed in a custom plastic package that uses a U-shaped leadframe to reduce the common mode fields generated as current flows through the current-carrying conductor. With the U-shaped leadframe, the stray fields cancel one another thus reducing electromagnetic interference (EMI).

Also, a good PCB layout of the CT426 will optimize performance and reduce EMI. See the Applications Information section in this datasheet for recommendations on PCB layout.

#### Creepage and Clearance

Two important terms as it relates to isolation provided by the package are: creepage and clearance. Creepage is defined as the

shortest distance across the surface of the package from one side the leads to the other side of the leads. The definition for clearance is the shortest distance between the leads of opposite side through the air. Figure 39 illustrates the creepage and clearance for the SOIC-8 package of the CT426.

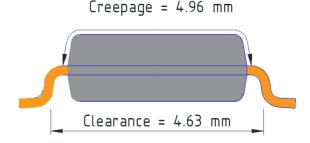


Figure 39: The Creepage and Clearance for the CT426 SOIC-8 package

### **Application**

The CT426 is an integrated contact current sensor that can be used in many applications from measuring current in power supplies to motor control to overcurrent fault protection. It is a plugand-play solution in that no calibration is required, and it outputs to a microcontroller a simple linear analog output voltage which corresponds to a current measurement value.

It is designed to support an operating voltage range of 3.0 to 3.6 V, but it is ideal to use a 3.3 V power supply where the output tolerance is less than  $\pm 5\%$ .

### **Bypass Capacitor**

A single 1.0  $\mu$ F capacitor is needed for the VCC pin to reduce the noise from the power supply and other circuits. This capacitor should be placed as close as possible to the CT426 to minimize inductance and resistance between the two devices.

#### Filter Capacitor

A capacitor may be added to the FILTER pin of the CT426 if there is a requirement to improve the noise performance. The capacitor will be connected to an internal resistor of 15 k $\Omega$  inside the chip to form a R-C filter. This R-C filter produces a cutoff frequency that will reduce the noise over this lower bandwidth.

If the filtering function is not required, then the FILTER pin should be left unconnected (No Connect).



### **Recommended PCB Layout**

Since the CT426 can measure up to 65 A of current, special care must be taken in the printed circuit board (PCB) layout of the CT426 and the surrounding circuitry. It is recommended that the CCC pins be connected to as much copper area as possible. It is also recommended that 2 oz. or heavier copper be used for PCB traces when the CT426 is used to measure up to 30 A of current. Additional layers of the PCB should also be used to carry current and be connected using the arrangement of vias. Figure 40 and Figure 41 show the recommended the PCB layout for the 20 A and 30 A variants of CT426. For the 65 A variant, it is recommended that 4 oz. of copper be used for the PCB traces.

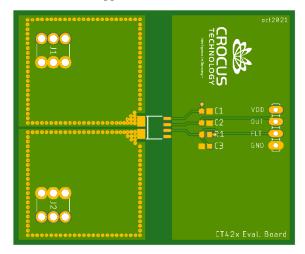


Figure 40: Recommended PCB Layout (Top Layer) for the 20 A to 65 A variants of the CT426

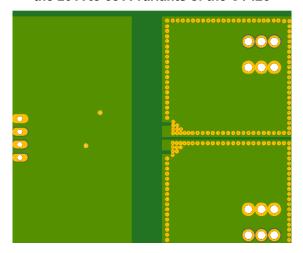
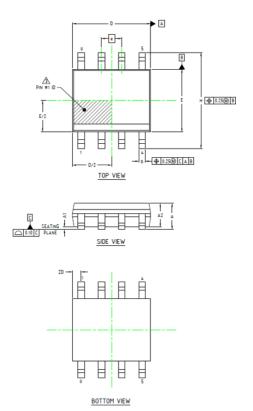
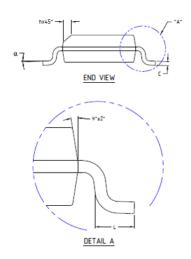


Figure 41: Recommended PCB Layout (Bottom Layer) for the 20 A to 65 A variants of the CT426



### PACKAGE OUTLINE DRAWING





#### NOTES

- 1. ALL DIMENSIONS IN MM.

- 1. ALL DIMENSIONS IN MM.
  2. PACKAGE SURFACE FINISHING:
  2.1 TOP: MATTE (CHARMILLES #18-30)
  2.2 BOTTOM: "MATTE (CHARMILLES #12-27)
  3. THE PIN #1 IDENTIFIER MUST BE LOCATED WITHIN THE ZONE INDICATED.

  INDICATED.
- 4. LEAD COPLANARITY SHOULD BE 0 TO 0.10MM MAX.
  5. JEDEC REFERENCE : MS-012.

Figure 42: SOIC-8 Package Drawing and Dimensions

Table 2: CT426 SOIC-8 Package Dimensions

Symbol		Dimensions in Millimeters (mm)					
Symbol	Min.	Тур.	Max.				
A1	0.10	0.18	0.25				
b	0.36	0.41	0.46				
С	0.19	0.22	0.25				
D	D 4.80 4.89		4.98				
Е	3.81	3.90	3.99				
е	1.27 BSC						
Н	5.80	6.00	6.20				
h	0.25	0.37	0.50				
L	0.41	_	1.27				
А	1.52	1.62	1.72				
α	0°	-	8°				
ZD		0.53 REF					
A2	1.37	1.47	1.57				

P1

W

12.00

16.00

+/- 0.10

+0.30 / -0.10

# XtremeSense™ TMR Current Sensor with Ultra-Low Noise and <0.7% Total Error

#### TAPE AND REEL POCKET DRAWING AND DIMENSIONS Do Ø 1.50 +0.10 1.75 ± 0.10 0.30 ± 0.03 2.00 ± 0.10 (I) 4.00 ± 0.10 (II) Ø 1.50 \*0.20 $\equiv$ ш 3 R0.30 3.40 PI MAX SECTION Y-Y q SECTION X-X Measured from centreline of sprocket to centreline of pocket Ao 6.35 +/- 0.10 Cumulative tolerance of 10 sprocket Во 5.13 +/- 0.10 holes is ± 0.20 2.25 +/- 0.15 Ko Measured from centreline of sprocket hole to centreline of pocket. 1.75 +/- 0.10 K1 Other material available. 7.50 +/- 0.10

Figure 43: Tape and Pocket Drawing for SOIC-8 Package

Dimension with ( ) is used for design reference purposes,

ALL DIMENSIONS IN MILLIMETRES UNLESS OTHERWISE STATED.

No measurement required.

#### **PACKAGE INFORMATION**

Table 3: CT426 Package Information

Part Number	Package Type	# of Leads	Package Quantity	Lead Finish	MSL Rating <sup>[2]</sup>	Operating Temperature (°C) [3]	Device Marking <sup>[4]</sup>
CT426-HSN820DR	SOIC	8	2000	Sn	3	-40 to 125	CT426 S820DR YYWWLL
CT426-ASN820DR	SOIC	8	2000	Sn	3	-40 to 125	CT426A S820DR YYWWLL
CT426-HSN820MR	SOIC	8	2000	Sn	3	-40 to 125	CT426 S820MR YYWWLL
CT426-ASN820MR	SOIC	8	2000	Sn	3	-40 to 125	CT426A S820MR YYWWLL
CT426-HSN830DR	SOIC	8	2000	Sn	3	-40 to 125	CT426 S830DR YYWWLL
CT426-ASN830DR	SOIC	8	2000	Sn	3	-40 to 125	CT426A S830DR YYWWLL
CT426-HSN830MR	SOIC	8	2000	Sn	3	-40 to 125	CT426 S830MR YYWWLL
CT426-ASN830MR	SOIC	8	2000	Sn	3	-40 to 125	CT426A S830MR YYWWLL
CT426-HSN850DR	SOIC	8	2000	Sn	3	-40 to 125	CT426 S850DR YYWWLL
CT426-ASN850DR	SOIC	8	2000	Sn	3	-40 to 125	CT426A S850DR YYWWLL
CT426-HSN850MR	SOIC	8	2000	Sn	3	-40 to 125	CT426 S850MR YYWWLL
CT426-ASN850MR	SOIC	8	2000	Sn	3	-40 to 125	CT426A S850MR YYWWLL
CT426-HSN865DR	SOIC	8	2000	Sn	3	-40 to 125	CT426 S865DR YYWWLL
CT426-ASN865DR	SOIC	8	2000	Sn	3	-40 to 125	CT426A S865DR YYWWLL
CT426-HSN865MR	SOIC	8	2000	Sn	3	-40 to 125	CT426 S865MR YYWWLL
CT426-ASN865MR	SOIC	8	2000	Sn	3	-40 to 125	CT426A S865MR YYWWLL

<sup>[1]</sup> RoHS is defined as semiconductor products that are compliant to the current EU RoHS requirements. It also will meet the requirement that RoHS substances do not exceed 0.1% by weight in homogeneous materials. Green is defined as the content of chlorine (CI), bromine (Br), and antimony trioxide based flame retardants satisfy JS709B low halogen requirements of ≤ 1,000 ppm.



<sup>[2]</sup> MSL Rating = Moisture Sensitivity Level Rating as defined by JEDEC standard classifications.

<sup>[3]</sup> Package will withstand ambient temperature range of -40°C to 125°C and storage temperature range of -65°C to 150°C.

<sup>[4]</sup> Device Marking for CT426 is defined as CT426 S8xxZR YYWWLL where the first 2 lines = part number, YY = year, WW = work week, and LL = lot code.

#### **DEVICE MARKING**

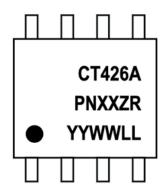


Figure 44: CT426 Device Marking for 8-lead Package

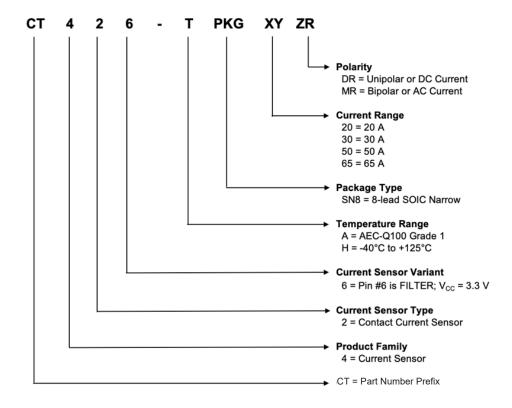
Table 4: CT426 Device Marking Definition for 8-lead SOIC Package Row No. Code Definition 3 Pin 1 Indicator 1 CT426 Allegro Part Number 1 Α AEC-Q100 Qualified 2 Ρ Package Type 2 Ν Number of Pins 2 XX **Current Range** 2 ZR Polarity ΥY 3 Calendar Year 3 WW Work Week

Lot Code

LL

#### PART ORDERING NUMBER LEGEND

3



**CT426** 

# XtremeSense™ TMR Current Sensor with Ultra-Low Noise and <0.7% Total Error

#### **Revision History**

Number	Date	Description
2	November 2, 2023	Document rebranded and minor editorial updates

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